

Example: Orthogonal Decomposition Theorem

Let $W = \text{Span}\left\{\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}\right\} \subseteq \mathbb{R}^4$. (These vectors form an orthogonal basis for W : check!)

and let $\mathbf{y} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$. Find the point in W closest to \mathbf{y} and find the distance from \mathbf{y} to W .

$$\begin{aligned}\widehat{\mathbf{y}} &= \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2 + \frac{\mathbf{y} \cdot \mathbf{u}_3}{\mathbf{u}_3 \cdot \mathbf{u}_3} \mathbf{u}_3 \\ &= \frac{\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}}{\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \frac{\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix}} \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix} + \frac{\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}}{\begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix}} \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix} \\ &= \frac{1}{1} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \frac{4}{6} \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix} + \frac{0}{2} \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix} = \frac{1}{1} \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \frac{2}{3} \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{4}{3} \\ 1 \\ \frac{2}{3} \\ \frac{2}{3} \end{bmatrix} = \text{the point in } W\end{aligned}$$

closest to \mathbf{y} .

$\begin{bmatrix} \frac{4}{3} \\ 1 \\ \frac{2}{3} \\ \frac{2}{3} \end{bmatrix}$ is the “best approximation” to $\mathbf{y} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ using a point from W .

$$\begin{aligned}\text{The distance from } \mathbf{y} \text{ to } W &= \|\mathbf{z}\| = \|\mathbf{y} - \widehat{\mathbf{y}}\| = \left\| \begin{bmatrix} -\frac{1}{3} \\ 0 \\ \frac{1}{3} \\ \frac{1}{3} \end{bmatrix} \right\| \\ &= \sqrt{\frac{1}{9} + \frac{1}{9} + \frac{1}{9}} = \frac{1}{\sqrt{3}} = \frac{\sqrt{3}}{3}.\end{aligned}$$

We can also think of $\|\mathbf{y} - \widehat{\mathbf{y}}\|$ as being the error committed when $\widehat{\mathbf{y}}$ is used as an approximation for \mathbf{y} . If $\mathbf{v} \in W$ and $\mathbf{v} \neq \widehat{\mathbf{y}}$, then $\|\mathbf{y} - \mathbf{v}\| > \frac{\sqrt{3}}{3}$.

Example (continuation from first side)

An orthonormal basis for the same subspace W of \mathbb{R}^4 can be obtained by normalizing the original basis to get

$$\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2/\sqrt{6} \\ 0 \\ 1/\sqrt{6} \\ 1/\sqrt{6} \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \right\}$$

$$\text{Let } U = \begin{bmatrix} 0 & 2/\sqrt{6} & 0 \\ 1 & 0 & 0 \\ 0 & 1/\sqrt{6} & -1/\sqrt{2} \\ 0 & 1/\sqrt{6} & 1/\sqrt{2} \end{bmatrix} \text{ and } U^T = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 2/\sqrt{6} & 0 & 1/\sqrt{6} & 1/\sqrt{6} \\ 0 & 0 & -1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

$$\text{Then } UU^T = \begin{bmatrix} \frac{2}{3} & 0 & \frac{1}{3} & \frac{1}{3} \\ 0 & 1 & 0 & 0 \\ \frac{1}{3} & 0 & \frac{2}{3} & -\frac{1}{3} \\ \frac{1}{3} & 0 & -\frac{1}{3} & \frac{2}{3} \end{bmatrix}$$

UU^T is 4×4 and defines a mapping $T : \mathbb{R}^4 \rightarrow \mathbb{R}^4$, $T(\mathbf{y}) = UU^T \mathbf{y}$

UU^T is the matrix from the orthogonal projection mapping of \mathbb{R}^4 onto W :

$$UU^T \mathbf{y} = \hat{\mathbf{y}}$$

$$\text{For example, from the other side, } UU^T \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{4}{3} \\ 1 \\ \frac{2}{3} \\ \frac{2}{3} \end{bmatrix}.$$

The range (= column space) for UU^T is the subspace W of \mathbb{R}^4 .