## MATH 233 LECTURE 4 (§12.5, CONT'D): LINES AND PLANES IN SPACE: INTERSECTIONS, ANGLES, DISTANCE

## Intersections.

- Two distinct planes: given  $\mathbb{P}_1$  and  $\mathbb{P}_2$ , with normal vectors  $\vec{n}_1$  and  $\vec{n}_2$ , there are two possibilities. Either  $\mathbb{P}_1$  and  $\mathbb{P}_2$  are parallel  $(\vec{n}_1$  is a scalar multiple of  $\vec{n}_2$ ), or they intersect in a line  $\ell$ . In the latter case, the direction vector  $\vec{v}$  of  $\ell$  is given by  $\vec{n}_1 \times \vec{n}_2$ . By finding a point P in the intersection, you can then obtain an equation of  $\ell$ .
- Line and plane: if the direction vector of  $\ell$  is not "in" the plane  $\mathbb{P}$  (i.e.  $\ell \cdot \vec{n} \neq 0$ ), then  $\ell$  intersects  $\mathbb{P}$  in a point. You can find this point by using the parametric equations of  $\ell$ , and solving for the value of t for which x(t), y(t), z(t) satisfy the equation of  $\mathbb{P}$ .
- Two distinct lines: given  $\ell_1$  and  $\ell_2$ , they may or may not intersect. You may determine this by writing the parametric equations of  $\ell_1$  [resp.  $\ell_2$ ] in terms of t [resp. s], then trying to solve for s and t such that the x, y, z values coincide (3 equations in 2 variables). If they do not intersect, and they are not parallel (parallel means that the direction vector  $\vec{v}_1$  is a scalar multiple of  $\vec{v}_2$ ), then  $\ell_1$  and  $\ell_2$  are called skew lines.

## Angles.

- Two planes: the angle between  $\mathbb{P}_1$  and  $\mathbb{P}_2$  is just the angle between  $\vec{n}_1$  and  $\vec{n}_2$ .
- Line and plane: find the (acute) angle  $\alpha$  between  $\vec{v}$  (direction vector of  $\ell$ ) and  $\vec{n}$  (normal vector of  $\mathbb{P}$ ). Then the angle between  $\ell$  and  $\mathbb{P}$  is  $\theta = 90^{\circ} \alpha$ .
- Two intersecting lines: this is easy.

## Distance.

ullet Point to plane: the distance from  $Q(x_1,y_1,z_1)$  to the plane  $\mathbb P$  with equation ax+by+cz+d=0 is given by

$$d(Q, \mathbb{P}) = \operatorname{comp}_{\vec{n}} \overrightarrow{PQ} = \frac{|ax_1 + by_1 + cz_1 + d|}{\sqrt{a^2 + b^2 + c^2}},$$

where P is any point on  $\mathbb{P}$ .

- Point to line: see your homework.
- Two parallel planes or skew lines: see next lecture.