

4.2.2 a.

$$\begin{bmatrix} 1 & 2 & 1 & 0 \\ -1 & 3 & 0 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 5 & 1 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 & 0 \\ 0 & 1 & \frac{1}{5} & \frac{1}{5} \end{bmatrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 0 & \frac{3}{5} & -\frac{2}{5} \\ 0 & 1 & \frac{1}{5} & \frac{1}{5} \end{bmatrix}, \quad \text{so } A^{-1} = \frac{1}{5} \begin{bmatrix} 3 & -2 \\ 1 & 1 \end{bmatrix}.$$

b.

$$\begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 1 & 1 & 2 & 0 & 1 & 0 \\ 0 & 1 & 2 & 0 & 0 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -1 & -1 & -1 & 1 & 0 \\ 0 & 1 & 2 & 0 & 0 & 1 \end{bmatrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 0 & 4 & -3 & -3 \\ 0 & 1 & 0 & 2 & -2 & -1 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & 2 & -2 & -1 \\ 0 & 0 & 1 & -1 & 1 & 1 \end{bmatrix}, \quad \text{so } A^{-1} = \begin{bmatrix} 0 & 1 & -1 \\ 2 & -2 & -1 \\ -1 & 1 & 1 \end{bmatrix}.$$

c.

$$\begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 1 & 0 \\ -1 & 3 & 1 & 0 & 0 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 1 & 0 \\ 0 & 3 & 2 & 1 & 0 & 1 \end{bmatrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & -1 & 1 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 & 0 & 2 & -1 & 1 \\ 0 & 2 & 1 & 0 & 1 & 0 \\ 0 & 2 & 1 & 0 & 1 & 0 \end{bmatrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 3 & -2 \\ 0 & 1 & 1 & -1 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 & -3 & 2 & 2 \end{bmatrix}$$

$$\text{so } A^{-1} = \begin{bmatrix} -1 & 3 & -2 \\ -1 & 2 & -1 \\ 2 & -3 & 2 \end{bmatrix}.$$

4. IMPLICIT AND EXPLICIT SOLUTIONS OF LINEAR SYSTEMS

4.2 d.

$$\left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 4 & 5 & 6 & 0 & 1 & 0 \\ 7 & 8 & 9 & 0 & 0 & 1 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -3 & -6 & -4 & 1 & 0 \\ 0 & -6 & -12 & -7 & 0 & 1 \end{array} \right]$$

$$\rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & -3 & -6 & -4 & 1 & 0 \\ 0 & 0 & 0 & 1 & -2 & 1 \end{array} \right], \text{ and so we see that } A^{-1} \text{ does not exist.}$$

$$\text{e. } \left[\begin{array}{ccc|ccc} 2 & 3 & 4 & 1 & 0 & 0 \\ 2 & 1 & 1 & 0 & 1 & 0 \\ -1 & 1 & 2 & 0 & 0 & 1 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & -1 & -2 & 0 & 0 & -1 \\ 2 & 3 & 4 & 1 & 0 & 0 \\ 2 & 1 & 1 & 0 & 1 & 0 \end{array} \right]$$

$$\rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & -1 & -2 & 0 & 0 & -1 \\ 0 & 5 & 8 & 1 & 0 & 2 \\ 0 & 3 & 5 & 0 & 1 & 2 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & -1 & -2 & 0 & 0 & -1 \\ 0 & -1 & -2 & 1 & -2 & -2 \\ 0 & 3 & 5 & 0 & 1 & 2 \end{array} \right]$$

$$\rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & -1 & -2 & 0 & 0 & -1 \\ 0 & 1 & 2 & -1 & 2 & 2 \\ 0 & 3 & 5 & 0 & 1 & 2 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & -1 & -2 & 0 & 0 & -1 \\ 0 & 1 & 2 & -1 & 2 & 2 \\ 0 & 0 & -1 & 3 & -5 & -4 \end{array} \right]$$

$$\rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & -1 & 0 & -6 & 10 & 7 \\ 0 & 1 & 0 & 5 & -8 & -6 \\ 0 & 0 & 1 & -3 & 5 & 4 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & 2 & 1 \\ 0 & 1 & 0 & 5 & -8 & -6 \\ 0 & 0 & 1 & -3 & 5 & 4 \end{array} \right],$$

$$\text{so } A^{-1} = \begin{bmatrix} -1 & 2 & 1 \\ 5 & -8 & -6 \\ -3 & 5 & 4 \end{bmatrix}.$$

$$4.2.3 \text{ a. (i) } A^{-1} = \begin{bmatrix} 5 & -3 \\ -3 & 2 \end{bmatrix}; \text{ (ii) } \mathbf{x} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}; \text{ (iii) } \mathbf{b} = 3 \begin{bmatrix} 2 \\ 3 \end{bmatrix} - \begin{bmatrix} 3 \\ 5 \end{bmatrix}.$$

$$\text{b. (i) } A^{-1} = \begin{bmatrix} -2 & 0 & 1 \\ 9 & -1 & -3 \\ -6 & 1 & 2 \end{bmatrix}; \text{ (ii) } \mathbf{x} = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}; \text{ (iii) } \mathbf{b} = 2 \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix}.$$

$$\text{c. (i) } A^{-1} = \begin{bmatrix} 1 & -1 & 0 \\ -1 & 0 & 1 \\ 1 & 1 & -1 \end{bmatrix}; \text{ (ii) } \mathbf{x} = \begin{bmatrix} 3 \\ -2 \\ 2 \end{bmatrix}; \text{ (iii) } \mathbf{b} = 3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} + 2 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

$$\text{d. (i) } A^{-1} = \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -3 & 2 \\ 0 & 0 & 4 & -3 \\ 0 & 0 & -1 & 1 \end{bmatrix}; \text{ (ii) } \mathbf{x} = \begin{bmatrix} 2 \\ -1 \\ 1 \\ 0 \end{bmatrix}; \text{ (iii) } \mathbf{b} = 2 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}.$$

4.3.1 a. Correct: $2v_1 - v_3 = 0$.

b. Incorrect: v_2 cannot be written as a linear combination of v_1 and v_3 .

4.3.2 a. Suppose $c_1 \begin{bmatrix} 1 \\ 4 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 9 \end{bmatrix} = 0$. Since $\begin{bmatrix} 1 & 2 \\ 4 & 9 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, we see that $c_1 = c_2 = 0$. Thus, $\left\{ \begin{bmatrix} 1 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ 9 \end{bmatrix} \right\}$ is linearly independent.

b. Suppose $c_1 \begin{bmatrix} 1 \\ 4 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 9 \\ 0 \end{bmatrix} = 0$. From $\begin{bmatrix} 1 & 2 \\ 4 & 9 \\ 0 & 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$, we see that $c_1 = c_2 = 0$. Thus, $\left\{ \begin{bmatrix} 1 \\ 4 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 9 \\ 0 \end{bmatrix} \right\}$ is linearly independent.

c. Suppose $c_1 \begin{bmatrix} 1 \\ 4 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 9 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix} = 0$. Since the reduced echelon form of

$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 9 & -2 \\ 0 & 0 & 0 \end{bmatrix}$ is $\begin{bmatrix} 1 & 0 & 31 \\ 0 & 1 & -14 \\ 0 & 0 & 0 \end{bmatrix}$, we see that this system has infinitely many solutions (e.g.,

$c_1 = -31, c_2 = 14, c_3 = 1$), and so the set $\left\{ \begin{bmatrix} 1 \\ 4 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 9 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \\ 0 \end{bmatrix} \right\}$ is linearly dependent.

d. Suppose $c_1 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 3 \\ 3 \end{bmatrix} + c_3 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = 0$. Since the echelon form of the matrix

$\begin{bmatrix} 1 & 2 & 0 \\ 1 & 3 & 1 \\ 1 & 3 & 2 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ has three pivots, we see that $c_1 = c_2 = c_3 = 0$ is the only

solution, and so the vectors form a linearly independent set.

e. Suppose $c_1 \begin{bmatrix} 1 \\ 1 \\ 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \\ 3 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ 3 \\ 1 \\ 1 \end{bmatrix} + c_4 \begin{bmatrix} 3 \\ 1 \\ 1 \\ 1 \end{bmatrix} = 0$. We find that

$$\begin{bmatrix} 1 & 1 & 1 & 3 \\ 1 & 1 & 3 & 1 \\ 1 & 3 & 1 & 1 \\ 3 & 1 & 1 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 & 1 & 3 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -10 \end{bmatrix},$$

so the only solution is the trivial solution. Thus, the vectors form a linearly independent set.

f. These vectors form a linearly dependent set. For example, their sum is 0.

4.3.3 Suppose $c_1(v - w) + c_2(2v + w) = 0$. Then $(c_1 + 2c_2)v + (c_2 - c_1)w = 0$. Since $\{v, w\}$ is linearly independent, we infer that $c_1 + 2c_2 = -c_2 + c_1 = 0$. But $\begin{bmatrix} 1 & 2 \\ -1 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$, so the only solution of this system is $c_1 = c_2 = 0$, as desired.

4.3.5 Suppose $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k = \mathbf{0}$. Then, for $i = 1, \dots, k$, $(c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k) \cdot \mathbf{v}_i = 0$, so $c_1(\mathbf{v}_1 \cdot \mathbf{v}_i) + \dots + c_i(\mathbf{v}_i \cdot \mathbf{v}_i) + \dots + c_k(\mathbf{v}_k \cdot \mathbf{v}_i) = c_i\|\mathbf{v}_i\|^2 = 0$. Since $\mathbf{v}_i \neq \mathbf{0}$, we must have $c_i = 0$ for $i = 1, \dots, k$. Hence $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ is linearly independent.

4.3.6 Suppose $k > n$, let $\mathbf{v}_1, \dots, \mathbf{v}_k \in \mathbb{R}^n$, and write $A = \begin{bmatrix} | & | & & | \\ \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_k \\ | & | & & | \end{bmatrix}$. Since $\text{rank}(A) \leq n < k$, the system $Ax = \mathbf{0}$ will have a nontrivial solution. Thus, $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ is linearly dependent. If we have k linearly independent vectors in \mathbb{R}^n , we conclude that $k \leq n$.

4.3.12 a. No: Since $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} - 2 \begin{bmatrix} 2 \\ 4 \\ 5 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \mathbf{0}$, the vectors form a linearly dependent set.

b. No: Any four vectors in \mathbb{R}^3 form a linearly dependent set.

c. No: Three vectors span a subspace whose dimension is at most 3.

4.3.14 To show that $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ is a basis for \mathbb{R}^n , it suffices by Proposition 3.9 to show that this is a linearly independent set of vectors.

a. From $\left[\begin{array}{cc|c} 2 & 3 & 3 \\ 3 & 5 & 4 \end{array} \right] \rightsquigarrow \left[\begin{array}{cc|c} 1 & 0 & 3 \\ 0 & 1 & -1 \end{array} \right]$, we see that $\{\mathbf{v}_1, \mathbf{v}_2\}$ is linearly independent and that $\mathbf{b} = 3\mathbf{v}_1 - \mathbf{v}_2$, so the coordinates of \mathbf{b} with respect to this basis are $\begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \end{bmatrix}$.

4.3.26 The polynomials $p_j(x) = x^j$, $j = 0, 1, \dots, k$, evidently span the space in question. We must only argue that they form a linearly independent set. Now suppose $c_0p_0 + c_1p_1 + \dots + c_kp_k = \mathbf{0}$, i.e., $c_0 + c_1x + c_2x^2 + \dots + c_kx^k = 0$ for all $x \in \mathbb{R}$. Evaluating at $x = 0$, we see immediately that $c_0 = 0$. Since all the derivatives of the 0-function are again identically 0, differentiating repeatedly and evaluating at $x = 0$ gives $c_1 = 0, c_2 = 0, \dots, c_k = 0$, as required.

Alternatively, evaluating at $x = 0$ gives $c_0 = 0$. Now we have $c_1x + c_2x^2 + \dots + c_kx^k = x(c_1 + c_2x + \dots + c_kx^{k-1}) = 0$ for all x , so $c_1 + c_2x + \dots + c_kx^{k-1} = 0$ for all x , from which we conclude that $c_1 = 0$. Continuing in this fashion, we have $c_0 = c_1 = \dots = c_k = 0$, as we needed.