# Sample Path Regularity for One-Dimensional Diffusion Processes

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## 1. Basic Assumptions. Assume that

(i)  $\{T_t\}$  is a strongly-continuous semigroup of bounded linear operators on the Banach space

$$B = C_0(I) = \{ f \text{ continuous on } I = [0, 1] : f(0) = f(1) = 0 \}$$

(ii) If  $f(x) \ge 0$  and  $f \in B$ , then  $T_t f(x) \ge 0$  and  $T_t f(x) \le \max_{y \in I} f(y)$ .

In general, the infinitesimal generator of a strongly-continuous semigroup of linear operators  $T_t$  on any Banach space B is defined by

$$Af = \lim_{h \to 0} (T_h f - f)/h \tag{1.1}$$

on the set

$$\mathcal{D} = \mathcal{D}(A) = \{f : \text{The limit in } (1.1) \text{ exists in the norm of } B\}$$

Suppose further that

(iii) The operator A and set  $\mathcal{D}(A)$  satisfy the following conditions. Let

$$Lf(x) = \frac{d}{dm(x)}\frac{d}{ds(x)}f(x)$$
(1.2)

for  $f \in C^2(I_0)$ , where  $C^2(I_0)$  is the set of all functions on  $I_0 = (0, 1)$  that are twice-continuously differentiable on  $I_0$ . In (1.2), s(x) is strictly increasing, continuously differentiable, and bounded on (0, 1), s'(x) > 0 on (0, 1), and the measure m(dx) = m(x)dx where m(x) is continuously and m(x) > 0 on (0, 1). Thus we can also write

$$Lf(x) = \frac{1}{m(x)} \frac{d}{dx} \frac{1}{s'(x)} \frac{d}{dx} f(x)$$
(1.3)

If  $f \in C^2(I_0) \cap C_0(I)$  and  $Lf \in C_0(I)$ , then  $f \in \mathcal{D}(A)$  and Af = Lf.

(iv) Since s(x) is strictly increasing and bounded on (0, 1), we can assume without loss of generality that s(0) = s(0+) = 0 and s(1) = s(1-) = 1. We also assume

$$\int_{0}^{x_{0}} s(x)m(dx) + \int_{x_{0}}^{1} (1-s(x))m(dx) < \infty$$
 (1.4)

whenever  $0 < x_0 < 1$ . In terms of diffusion process theory, this is the condition that the endpoints are regular or exit.

### 2. Some Useful Identities. (1) Define

$$g(x,y) = \frac{\left(s(1) - s(x \lor y)\right)\left(s(x \land y) - s(0)\right)}{s(1) - s(0)}$$
(2.1)

where  $0 \le x, y \le 1, x \land y = \min\{x, y\}$ , and  $x \lor y = \max\{x, y\}$ . Let

$$f(x) = \int_{0}^{1} g(x, y)h(y)m(dy)$$
(2.2)

$$= \frac{s(1) - s(x)}{s(1) - s(0)} \int_0^x (s(y) - s(0))h(y)m(dy) + \frac{s(x) - s(0)}{s(1) - s(0)} \int_x^1 (s(1) - s(y))h(y)m(dy)$$
(2.3)

where h(y) is bounded on  $I_0$ . By (2.1)

$$g(x,y) \leq \min\{g(x,x), g(y,y)\}$$

$$g(y,y) \leq \min\{s(1) - s(y), s(y) - s(0)\}$$
(2.4)

If  $h(y) \ge 0$ , then by (2.2) and (2.4)

$$f(x) \leq \int_{0}^{1} g(y,y)h(y)m(dy)$$

$$\leq \int_{0}^{1} \min\{s(1) - s(y), s(y) - s(0)\}h(y)m(dy)$$

$$= \int_{0}^{x_{0}} (s(y) - s(0))h(y)m(dy) + \int_{x_{0}}^{1} (s(1) - s(y))h(y)m(dy)$$
(2.5)
(2.5)

where  $x_0$  is determined by  $s(x_0) - s(0) = (1/2)(s(1) - s(0))$ . It then follows from (1.4) that f(x) in (2.2) is uniformly bounded with

$$|f(x)| \leq C \max_{y} |h(y)| \tag{2.7}$$

where C is the constant on the right-hand-side value of (2.6) if h(y) is replaced by 1. It follows similarly from (2.4) and the dominated convergence theorem that  $f(x) \in C(I)$  with f(0) = f(1) = 0.

(2) If  $h(x) \in C_0(I)$ , then f(x) in (2.2) is continuous differentiable with

$$f'(x) = s'(x) \left( \int_x^1 \frac{s(1) - s(y)}{s(1) - s(0)} h(y) m(dy) - \int_0^x \frac{s(y) - s(0)}{s(1) - s(0)} h(y) m(dy) \right)$$

Hence f'(x)/s'(x) is continuously differentiable with

$$Lf(x) = \frac{1}{m(x)} \frac{d}{dx} \left( \frac{f'(x)}{s'(x)} \right) = -h(x)$$

Then, by Assumption (iii),  $f \in \mathcal{D}(A)$  and Af = Lf = -h. In fact, it is not difficult to show that if  $f(x) \in C^2(I_0) \cap C_0(I)$  and  $Lf = -h \in C_0(I)$ , then f(x) is given by (2.2). (*Exercise:* Prove the last statement. Lemma 8.1 in Section 8 below has a second proof using martingales.)

(3) Another useful identity is

$$T_t f(x) = f(x) + \int_0^t T_s(Af)(x) ds, \quad \text{any } f \in \mathcal{D}(A)$$
(2.8)

This follows immediately from the definition (1.1) and the strong continuity of the semi-group.

(4) If 
$$||T_t|| \leq Ce^{Mt}$$
 and

$$R_{\lambda}f(x) = \int_0^\infty e^{-\lambda t} T_t f(x) dt, \qquad \lambda > M$$
(2.9)

then applying  $R_{\lambda}$  to the identity (2.8) and rearranging terms implies

$$R_{\lambda}(\lambda I - A)f = f, \quad f \in \mathcal{D}(A)$$

Similarly, if  $g = R_{\lambda} f$  for  $f \in B$ , it follows from the strong continuity of  $\{T_t\}$  that  $g \in \mathcal{D}(A)$  and  $Ag = \lambda g - f$ . Thus  $(\lambda I - A)R_{\lambda}f = f$  for all  $f \in B$ . It follows that  $\lambda I - A$  on  $\mathcal{D} = \mathcal{D}(A)$  is a two-sided inverse of  $R_{\lambda}$  on B.

**3. A Probability Space for T\_t.** By Assumptions (i) and (ii), we can write

$$T_t f(x) = \int_0^1 f(y) P(t, x, dy)$$
(3.1)

where  $P(t, x, dy) \ge 0$  are Borel measures on the open unit interval  $I_0 = (0, 1)$ . The semigroup property  $T_{t+s}f = T_tT_sf$  for  $\{T_t\}$  is equivalent to the Chapman-Kolmogorov equations

$$P(t+s,x,B) = \int_0^1 P(t,y,B)P(s,x,dy)$$
(3.2)

for P(t, x, dy). The assumptions in Section 1 imply  $0 \le P(t, x, I_0) \le 1$ , but do not exclude the possibility  $P(t, x, I_0) < 1$ .

The first step in finding a stochastic process corresponding to the semigroup (3.1) is to extend P(t, x, A) on  $I_0 = (0, 1)$  to a larger space  $I_{\Delta}$  such that (i)  $P(t, x, I_{\Delta}) = 1$  for all  $x \in I_{\Delta}$  and (ii) the Chapman-Kolmogorov equations (3.2) hold on  $I_{\Delta}$ . To do this, we first define an abstract "death point"  $\Delta \notin I_0$  and set

$$I_{\Delta} = I_0 \cup \{\Delta\}, \qquad I_0 = (0, 1)$$
 (3.3)

We extend P(t, x, A) for  $x \in I_0, A \subseteq I_0$  to  $x \in I_\Delta, A \subseteq I_\Delta$  by

$$P(t, x, \{\Delta\}) = 1 - P(t, x, I_0)$$

$$P(t, \Delta, \{\Delta\}) = 1, \qquad P(t, \Delta, I_0) = 0$$
(3.4)

Then the extended function P(t, x, A) for  $x \in I_{\Delta}$  and  $A \subseteq I_{\Delta}$  satisfies (i)  $P(t, x, A) \ge 0$ , (ii)  $P(t, x, I_{\Delta}) = 1$  for all  $x \in I_{\Delta}$ , and (iii) the Chapman-Kolmogorov relations

$$P(t+s,x,B) = \int_{I_{\Delta}} P(t,y,B)P(s,x,dy)$$
(3.5)

for  $x \in I_{\Delta}$  and  $B \subseteq I_{\Delta}$ . (*Exercise:* Prove (i,ii,iii) using (3.4) and (3.2) on  $I_{0}$ .)

Let  $Q = \{k/2^m : k \ge 0, m \ge 0\}$  be the set of nonnegative dyadic rationals. We will use the Kolmogorov Consistency Theorem (KCT) to construct a probability space  $(\Omega, \mathcal{F}, P_x)$  with random variables  $\{X_q(\omega) \in I_\Delta : q \in Q\}$ that form a Markov process consistent with (3.3), (3.4), and (3.5). The subscript x in  $P_x$  is a parameter  $x \in I_\Delta$  for which  $P_x(X_0 = x) = 1$ . In the Kolmogorov representation, the basic sample space is the infinite product

$$\Omega = (I_C)^Q = \{ \omega : \omega = \omega(r) \in I_C, \ r \in Q \}$$
(3.6)

where  $I_C = [0, 1] \cup \{\Delta\}$  is a compact version of  $I_{\Delta}$ . The random variables  $X_r(\omega) = \omega(r)$  are the coordinate functions in the infinite product  $\Omega$ . The sigma-algebra  $\mathcal{F} = \mathcal{B}\{X_r : r \in Q\}$  is the smallest sigma-algebra of subsets of  $\Omega$  with respect to which all  $X_r$  are measurable. This is also the sigma algebra generated by the *cylinder sets* 

$$\Gamma(r_1, \dots, r_n, A_1, \dots, A_n) = \{ \omega : X_{r_i}(\omega) \in A_i \text{ for } 1 \le i \le n \}$$
(3.7)

for  $0 \leq r_1 < r_2 < \ldots < r_n$  for  $r_i \in Q$ , sets  $A_i \subseteq I_C$ , and all n. The first step in applying the KCT is to define  $P_x$  for cylinder sets. The appropriate

definition in this case turns out to be the somewhat complex

$$P_x \Big( \Gamma(r_1, \dots, r_n, A_1, \dots, A_n) \Big)$$
  
=  $\int_{A_1} \dots \int_{A_n} P(r_1, x, dy_1) P(r_2 - r_1, y_1, dy_2) \dots$   
 $\dots P(r_n - r_{n-1}, y_{n-1}, dy_n)$  (3.8)

We assume in (3.8) that  $P_x(X_0 = x) = 1$  if  $r_1 = 0$ ,  $P(t, 0, \{0\}) = P(t, 1, \{1\}) = 1$  for  $t \ge 0$ , and  $P(t, x, \{0, 1\}) = 0$  for  $x \in I_\Delta = (0, 1) \cup \{\Delta\}$ .

The next step is to notice that if (for example)  $A_{i_0} = I_C$  in (3.7), then  $P_x(\Gamma(r_1, \ldots, A_1, \ldots))$  is the same as if we dropped the  $i_0$ -th coordinate in (3.7) and (3.8) and computed the probability of the resulting cylinder set with n-1 conditions. (This is the *consistency condition* in the KCT.) Here the consistency condition follows from the Chapman-Kolmogorov relation

$$\int_{I_C} P(r_{i_0+1} - r_{i_0}, y, A) P(r_{i_0} - r_{i_0-1}, x, dy) = P(r_{i_0+1} - r_{i_0-1}, x, A)$$

which follows from (3.5).

The KCT then implies that there exists a unique probability measure  $P_x$ on  $(\Omega, \mathcal{F})$  such that  $P_x(\Gamma(\ldots))$  is given by (3.8) for cylinder sets (3.7). One can then check from (3.8) that

$$P_x(X_r \in I_{\Delta}) = 1, \qquad x \in I_{\Delta} \subset I_C, \ r \in Q$$
  

$$P_x(X_r \in A) = P(r, x, A), \qquad x \in I_{\Delta}, \ A \subseteq I_{\Delta} \text{ and}$$
  

$$P_x(X_q \in A \mid \mathcal{B}_r)(\omega) = P(q - r, X_r(\omega), A)$$
(3.9)

for  $r, q \in Q$ , r < q, and  $x \in I_{\Delta}$ . Here  $\mathcal{B}_r = \mathcal{B}\{X_a : a \leq r, a \in Q\}$ is the smallest  $\sigma$ -algebra  $\mathcal{B}_r \subseteq \mathcal{F}$  such that  $X_a(\omega)$  is  $\mathcal{B}_r$ -measurable for  $a \leq r, a \in Q$ . Here  $P_x(X_q \in A \mid \mathcal{B}_r)(\omega)$  is the conditional-probability random variable. That is,  $g(\omega) = P_x(X_q \in A \mid \mathcal{B}_r)(\omega)$  is the unique bounded  $\mathcal{B}_r$ -measurable function such that

$$E(I_A(X_q)h) = E((P(q-r, X_r, A)h))$$

for all bounded  $\mathcal{B}_r$ -measurable random variables  $h(\omega)$ . (*Exercise:* Verify (3.9).)

The relations (3.9) imply that, for a set of  $\omega \in \Omega$  with  $P_x$ -probability one for every  $x \in I_{\Delta} = (0, 1) \cup \{\Delta\}$ , the sample paths  $\{X_r(\omega) : r \in Q\}$  start in and remain in  $I_{\Delta}$ . Thus  $\{X_r : r \in Q\}$  is a Markov stochastic process with values in  $I_{\Delta}$  and Markov transition function P(t, x, A).

Similarly, (3.4) implies that, again for a set of  $\omega$  with  $P_x$ -probability one for every  $x \in I_{\Delta}$ ,  $X_r(\omega) = \Delta$  for any  $\omega$  implies  $X_q(\omega) = \Delta$  for every q > r. Set  $\zeta(\omega) = \min\{r \in Q : X_r(\omega) = \Delta\}$ . We call  $\zeta(\omega)$  the *death time* for a sample path  $X_r(\omega)$  in  $I_0$ . For these  $\omega \in \Omega$ ,  $X(r, \omega) = \Delta$  whenever  $r > \zeta(\omega)$ . Thus, within sets of probability zero,

$$\{\omega: \zeta(\omega) > r\} = \{\omega: X_r(\omega) \in I_0\}$$

This implies that by (3.1) and (3.3)–(3.4)

$$T_r f(x) = \int_0^1 f(y) P(r, x, dy) = E_x (f(X_r) I_{[X_r \in I_0]})$$
  
=  $E_x (f(X_r) I_{[\zeta > r]})$  (3.10)

The purpose for restricting r to a countable set is so that events involving the sample paths  $X_r(\omega)$  depend on at most a countably infinite number of random variables. Otherwise, simple events involving sample-path continuity or even Lebesgue measurability may not be measureable.

The next step will be to extend  $\{X_r : r \in Q\}$  to random variables  $\{X_t : t \geq 0\}$  defined on the same probability space in such a way that events involving the process  $\{X_t : t \ge 0\}$  will depend only on  $\{X_r : r \in Q\}$ .

# 4. Sample Path Regularity. As in (2.2),

$$f(x) = \int_0^1 g(x, y)h(y)m(dy)$$
(4.1)  
=  $(1 - s(x))\int_0^x s(y)h(y)m(dy) + s(x)\int_x^1 (1 - s(y))h(y)m(dy)$ 

for  $h \in C_0(I)$ . Define functions  $\phi_N(x) \in C_0(I)$  for  $N \geq 3$  such that  $\phi_N(x) = 0$  for  $x < 1 - 1/N, \ \phi_N(x) \ge 0$ ,

$$\operatorname{Supp}(\phi_N) \subseteq \left(1 - \frac{1}{N}, 1 - \frac{1}{2N}\right)$$

and  $\int_{0}^{1} (1 - s(y)) \phi_{N}(y) m(dy) = 1$ . Define

$$f_N(x) = \int_0^1 g(x, y)\phi_N(y)m(dy)$$
(4.2)

Then  $f_N \in \mathcal{D}(A)$ ,  $Af_N(x) = -\phi_N(x) \leq 0$ , and by (4.1)

$$f_N(x) = s(x)$$
 on  $\left(0, 1 - \frac{1}{N}\right)$  (4.3)

It follows from the identity (2.8) in Section 2 that

$$T_{t}f_{N}(x) = f_{N}(x) + \int_{0}^{t} T_{s}(Af_{N})ds$$
  
=  $f_{N}(x) - \int_{0}^{t} T_{s}\phi_{N}(x)ds$  (4.4)

Since  $\phi_N(x) \ge 0$  and  $f_N(x) \ge 0$  by (4.2),  $0 \le T_t f_N(x) \le f_N(x)$  for all  $t \ge 0$ and  $x \in I_0$ . Then by (3.10), (4.4), and the Markov property

$$E_x \Big( f_N(X_q) I_{[\zeta>q]} \mid \mathcal{B}_r \Big)(\omega) = T_{q-r} f_N \big( X_r(\omega) \big)$$

$$\leq f_N \big( X_r(\omega) \big) I_{[\zeta(\omega)>r]}$$
(4.5)

where  $\mathcal{B}_r = \mathcal{B}\{X_a : a \leq r, a \in Q\}$  as before. Since  $0 \leq f_N(x) \leq C_N$  by (4.2) and (2.7),

$$Y_r^N(\omega) = f_N(X_r(\omega))I_{[\zeta(\omega)>r]}, \qquad 0 \le r < \infty, \ r \in Q$$

is a uniformly bounded supermartingale for each N. Moreover, it follows from (4.3) and the conditional Fatou's inequality

$$E\left(\liminf_{N\to\infty}H_N\mid \mathcal{B}_r\right) \leq \liminf_{N\to\infty}E\left(H_N\mid \mathcal{B}_r\right) \text{ a.s.},$$

for arbitrary random variables  $H_N(\omega) \ge 0$  that (4.5) also holds with  $f_N(x)$  replaced by s(x). Thus

$$Y_r(\omega) = s \big( X_r(\omega) \big) I_{[\zeta(\omega) > r]} \qquad 0 \le r < \infty, \ r \in Q$$
(4.6)

is also a uniformly bounded supermartingale.

Doob's Upcrossing Inequality now applies to the finite subsets  $Q_{NM} = \{k/2^N : 0 \le k \le M\}$  of Q with a uniform upper bound. This in turn implies that there exists a single null set  $E \in \mathcal{F}$  such that for  $\omega \notin E$ , the limits

$$\lim_{q>t, q \downarrow t} X_q(\omega) = X_{t+}(\omega), \qquad \lim_{q < t, q \uparrow t} X_q(\omega) = X_{t-}(\omega)$$
(4.7)

exist for all real values  $t < \zeta(\omega)$ , where the first limit exists for t = 0, and the second limit exists at  $t = \zeta(\omega)$ . It follows from (4.7) that the set

$$\{t: t < \zeta(\omega), X_{t+}(\omega) \neq X_{t-}(\omega)\}$$

is at most countably infinite for each such  $\omega$ , even though the set of possible tin (4.7) is uncountably infinite. Since  $X_r(\omega) = \Delta$  almost surely for  $r \ge \zeta(\omega)$ , it follows that (4.7) holds for all real  $t \ge 0$  and  $\omega \notin E_1$  for a larger null set  $E_1$ .

We now define random variables  $X_t(\omega)$  for all real  $t \ge 0$  in terms of the random variables  $\{X_r(\omega) : r \in Q\}$  by

$$X_t(\omega) = \lim_{r>t, r\downarrow t} X_r(\omega) = X_{t+}(\omega), \quad 0 \le t < \zeta(\omega)$$

$$= \Delta, \quad \zeta(\omega) \le t < \infty$$
(4.8)

Note that this defines an uncountable number of random variables  $\{X_t(\omega)\}$  in terms of a countable set  $\{X_r(\omega) : r \in Q\}$ . The first relation in (4.7) implies that  $X_t(\omega)$  is right-continuous in t for all real  $t \geq 0$ . The relations (4.7) and (4.8) do not exclude  $X_t(\omega) \neq X_r(\omega)$  for t = r. However, the strong continuity condition on  $T_f(x)$  in Section 1 implies

$$\lim_{q>r, q\downarrow r} T_q f(x) = \lim_{q>r, q\downarrow r} E_x \left( f(X_q) I_{[\zeta>q]} \right) = T_r f(x) = E_x \left( f(X_r) I_{[\zeta>r]} \right)$$

uniformly in  $x \in I_0$  for all  $f \in B = C_0(I)$ . This implies  $\lim_{q>r, q \downarrow r} X_q = X_r$ weakly  $P_x$  for all  $x \in (0, 1)$ . Since the same limit converges a.s. to  $X_t$  by (4.7), it follows that  $P_x(X_t = X_r) = 1$  for t = r. Thus, with probability one, the sample paths  $\{X_t(\omega) : t \ge 0\}$  are right continuous in t. We will use another martingale argument below to show that, in fact, almost every sample path  $\{X_t(\omega)\}$  is continuous for  $t < \zeta(\omega)$ .

A subtlety of the definition (4.8) is that  $X_t(\omega)$  is not  $\mathcal{B}_t$ -measurable for  $\mathcal{B}_t = \mathcal{B}\{X_r : r \leq t\}$  even if  $t = r \in Q$ , since it involves a right-hand limit. However,  $X_t$  is  $\mathcal{B}_{t+}$  measurable for  $\mathcal{B}_{t+} = \bigcap_{\epsilon > 0} \mathcal{B}_{t+\epsilon}$ . The right-continuity of sample paths from (4.8) implies that  $X_t$  is a Markov process with respect to  $\mathcal{B}_{t+}$ : That is,

$$P_x(X_{t+s} \in A \mid \mathcal{B}_{t+}) = P(s, X_t(\omega), A) \text{ a.s.}$$

$$(4.9)$$

This follows from the relation

$$E_x\big(\phi(X_{t+s})\psi(X_{t_1},\ldots,X_{t_n})\big) = E_x\big(T_{s-\epsilon}\phi(X_{t_n})\psi(X_{t_1},\ldots,X_{t_n})\big) \quad (4.10)$$

for all  $\phi \in C_0(I)$ ,  $\psi \in C_0(I^n)$ , and  $0 < t_1 < t_2 < \ldots < t_n = t + \epsilon < t + s$ . The relation (4.10) follows from (3.5) and (3.8). Finally, let  $\epsilon \to 0$  in (4.10) and use the strong continuity of  $\{T_t\}$  and the right-continuity of sample paths  $X_t(\omega)$ . (*Exercise:* Carry out the details.)

5. A Family of Martingales. The key step in the last step was identifying a bounded supermartingale. Most of the following results will also depend on martingale arguments. Before continuing, we state a result about a set of martingales that we will use several times that arises naturally for any Markov process.

To keep things simple, first consider a discrete-time Markov proces  $X_n$ on a state space J with a transition function

$$P(X_{n+1} \in B \mid X_n = x) = \pi(x, B)$$

Since  $X_n$  is a Markov process,

$$P(X_{n+1} \in B \mid \mathcal{B}(X_1, X_2, \dots, X_n)) = \pi(X_n(\omega), B)$$
(5.1)

Define  $Tf(x) = \int_J f(y)\pi(x, dy) = E_x(f(X_1))$  and Af(x) = Tf(x) - f(x). Then  $T^n f(x) = E_x(f(X_n))$  by the Markov property, and

**Lemma 5.1.** For any bounded function f(x) on J, the process

$$Y_n = f(X_n) - \sum_{k=0}^{n-1} Af(X_k)$$
(5.2)

is a martingale with respect to the  $\sigma$ -algebras  $\mathcal{B}_n = \mathcal{B}(X_1, X_2, \dots, X_n)$ .

**Proof.** Assume n < m. Clearly  $\mathcal{B}_n \subseteq \mathcal{B}_m$  and  $Y_n$  is  $\mathcal{B}_n$ -measurable. Thus it only remains to prove  $E(Y_m | \mathcal{B}_n) = Y_n$  in order to show that  $\{Y_n, \mathcal{B}_n\}$  is a martingale. By (5.2)

$$Y_m = f(X_m) - \sum_{k=n}^{m-1} Af(X_k) - \sum_{k=0}^{n-1} Af(X_k)$$
$$= Y_m^{(1)} - Y_m^{(2)} - Y_m^{(3)}$$

Then

$$E(Y_m^{(1)} | \mathcal{B}_n) = E(f(X_n) | \mathcal{B}_n) = T_{m-n}f(X_n)$$
$$E(Y_m^{(2)} | \mathcal{B}_n) = \sum_{k=n}^{n-1} E(Af(X_k) | \mathcal{B}_n) = \sum_{k=n}^{n-1} T_{k-n}Af(X_n)$$

by (5.1) and the Markov property for  $X_n$ . Since Af = Tf - f,

$$E(Y_m^{(1)} \mid \mathcal{B}_n) - E(Y_m^{(2)} \mid \mathcal{B}_n) = T^{m-n} f(X_n) - \sum_{k=n}^{m-1} T^{k-n} A f(X_n)$$

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$$= T^{m-n}f(X_n) - \sum_{k=n}^{m-1} (T^{k-n+1}f(X_n) - T^{k-n}f(X_n))$$
  
=  $f(X_n)$ 

and  $E(Y_m^{(1)} - Y_m^{(2)} | \mathcal{B}_n) = f(X_n)$ . Since  $Y_m^{(3)} = \sum_{k=0}^{n-1} Af(X_k)$  is  $\mathcal{B}_n$ -measurable,

$$E(Y_m \mid \mathcal{B}_n) = E(Y_m^{(1)} - Y_m^{(2)} \mid \mathcal{B}_n) - E(Y_m^{(3)} \mid \mathcal{B}_n)$$
  
=  $f(X_n) - \sum_{k=0}^{n-1} g(X_k) = Y_n$ 

This completes the proof that  $\{Y_n, \mathcal{B}_n\}$  is a martingale.

**Lemma 5.2.** For any function  $f \in \mathcal{D}(A)$ , the process

$$Y_t(\omega) = f(X_t(\omega))I_{[\zeta(\omega)>t]} - \int_0^{t\wedge\zeta(\omega)} Af(X_s(\omega))ds$$
 (5.3)

is a martingale with respect to the sigma-algebras  $\{\mathcal{B}_{t+}\}$ .

**Proof.** By (2.8)

$$T_t f(x) = f(x) + \int_0^t T_s A f(x) ds$$
 (5.4)

for any  $f \in \mathcal{D}(A)$ . Since  $\Delta$  is a trap, any  $f \in \mathcal{D}(A)$  for the semigroup  $T_t f(x)$  for f(x) on  $I_0 = (0,1)$  can be extended to  $f \in \mathcal{D}(A)$  for f(x) on  $I_{\Delta} = (0,1) \cup \{\Delta\}$  by setting  $f(\Delta) = 0$ . By essentially the same argument as in the proof of Lemma 5.1 with (5.4) replacing a telescoping sum, this implies that the process

$$Y_t = f(X_t) - \int_0^t Af(X_s) ds$$
 (5.5)

is a continuous-parameter martingale with respect to  $\mathcal{B}_{t+}$ . Since  $\Delta$  is a trap,  $Af(\Delta) = 0$  for any  $f \in \mathcal{D}(A)$ . Thus the martingale (5.5) is the same as the process in (5.3).

**Exercise.** Complete the proof that (5.5) is a continuous-time martingale with respect to  $\mathcal{B}_{t+}$ . Give justifications for interchanging the order of integrals and conditional expectations.

### 6. An Upper Bound for Exit and Death Times. Let

$$T_N(\omega) = \min\left\{ t : t < \zeta(\omega), \ X_t(\omega) \in \left(0, \frac{1}{N}\right) \cup \left(1 - \frac{1}{N}, 1\right) \right\}$$
(6.1)

be the first time that  $X_t(\omega)$  exits from the closed interval [1/N, 1 - 1/N], assuming that it remains within  $I_0 = (0, 1)$ .

We make the the convention that  $T_N(\omega) = \infty$  if the right-hand side of (6.1) is empty; that is, if  $X_t(\omega) \notin (0, 1/N) \cup (1 - 1/N, 1)$  for all  $t < \zeta(\omega)$ . If  $T_N(\omega) < \infty$ , then  $T_N(\omega) < \zeta(\omega)$ .

Note that  $\{\omega: T_N(\omega) > t\} \in \mathcal{B}_{t+}$ . We may not have  $\{\omega: T_N(\omega) > t\} \in \mathcal{B}_t$  in general, either because  $t \notin Q$  (recall  $\mathcal{B}_t = \mathcal{B}\{X_q : q \leq t, q \in Q\}$ ) or because  $t = q \in Q$  but  $X_t = X_{q+} \neq X_q$ . Thus  $T_N$  may not be a  $\mathcal{B}_t$ -stopping time, but is a  $\mathcal{B}_{t+}$ -stopping time. However, Lemma 5.2 implies that  $Y_t(\omega)$  are martingales with respect to  $\mathcal{B}_{t+}$ , so that this is enough.

We then have

**Theorem 6.1.** If C is the constant in (2.7),

$$\max_{0 \le x \le 1} E_x(T_{\infty} \land \zeta) \le C, \qquad T_{\infty}(\omega) = \sup_N T_N(\omega)$$
(6.2)

where  $T_{\infty} \wedge \zeta = \min\{T_{\infty}, \zeta\}.$ 

Thus, with  $P_x$ -probability one for any  $x \in I_0$ , either  $T_{\infty}(\omega) < \infty$  or  $\zeta(\omega) < \infty$ . In particular, the only way that  $T_{\infty}(\omega) = \infty$  can happen is if  $\zeta(\omega) < \infty$ .

**Proof of Theorem 6.1.** Define continuous functions  $\psi_N \in C_0(I)$  such that  $0 \leq \psi_N(y) \leq 1$  and  $\psi_N(y) = 1$  on (1/N, 1 - 1/N). If

$$h_N(x) = \int_0^1 g(x, y)\psi_N(y)m(dy)$$
(6.3)

then  $h_N \in \mathcal{D}(A)$  and  $Ah_N = -\psi_N \leq 0$ . In particular,  $Ah_N(x) = -1$  on (1/N, 1 - 1/N). Thus by Lemma 5.2

$$Y_t^N = h_N(X_t) I_{[\zeta > t]} + \int_0^{t \wedge \zeta} \psi_N(X_s) ds$$
 (6.4)

is a nonnegative martingale for any  $N \ge 3$ . Then by the Optional Stopping Theorem,

$$Y_{t\wedge T_N}^N = h_N(X_{t\wedge T_N})I_{[\zeta > t\wedge T_N]} + \int_0^{t\wedge T_N \wedge \zeta} \psi_N(X_s)ds$$
$$= h_N(X_{t\wedge T_N})I_{[\zeta > t\wedge T_N]} + t\wedge T_N \wedge \zeta$$

are also martingales, since  $\psi(X_s) = 1$  for  $0 \leq s < T_N \wedge \zeta$ . This in turn implies

$$E_x(t \wedge T_N \wedge \zeta) = h_N(x) - E_x(h_N(X_{t \wedge T_N \wedge \zeta})) \leq C$$
(6.5)

since  $0 \leq \psi_N(x) \leq 1$  implies  $0 \leq h_N(x) \leq C$  by (6.3) where C is the same constant as in (2.7). Fatou's theorem applied to t and N (in any order) then implies (6.2).

7. Exit Times are Less Than Death Times. Death times  $\zeta(\omega)$  are necessary for general Markov processes, but can be shown to be less mysterious here. As in (6.1), let

$$T_N(\omega) = \min\left\{ t : t < \zeta(\omega), \ X_t(\omega) \in \left(0, \frac{1}{N}\right) \cup \left(1 - \frac{1}{N}, 1\right) \right\}$$
(7.1)

We show below that  $P_x(T_N < \zeta) = 1$ , so that  $T_N(\omega) < \zeta(\omega)$  almost surely. This implies that  $T_{\infty}(\omega) = \sup_N T_N(\omega) \le \zeta(\omega)$  with probability one. We will show in a later section that, in fact,  $T_{\infty}(\omega) = \zeta(\omega)$  almost surely.

The same argument as in Theorem 7.1 can also be used to show that the sample paths  $\{X_t(\omega)\}$  are continuous for  $0 \le t < \zeta(\omega)$  (see Theorem 7.2).

**Theorem 7.1.** For the process  $\{X_t\}$  defined above,

$$P_x(T_N < \zeta) = 1 \quad \text{for all } x \in (0, 1) \tag{7.2}$$

Corollary 7.1.

$$\max_{0 \le x \le 1} E_x(T_\infty) \le C, \qquad T_\infty(\omega) = \sup_N T_N(\omega)$$
(7.3)

Morever,  $\lim_{N\to\infty} X_{T_N}(\omega) = A$  exists almost surely where A (depending on  $\omega$ ) is either 0 or 1.

**Proof.** Equations (6.2) and (7.2) imply (7.3),  $\lim_{N\to\infty} X_{T_N}$  exists a.s. by (4.7), and  $X_{T_N} \in (0, 1/N) \cup (1 - 1/N, 1)$  by right-continuity of the sample paths.

**Proof of Theorem 7.1.** It is sufficient to assume 1/N < x < 1 - 1/Nsince  $T_N(\omega) = 0$  if  $x \in (0, 1/N) \cup (1 - 1/N, 1)$ . It follows from (3.10) and the strong continuity of the semi-group  $\{T_t\}$  that  $P_x(\zeta > 0) = 1$  for arbitrary  $x \in I_0$ .

Let  $\psi_N(x) \in C_0(I) \cap C^2(I)$  such that  $0 \leq \psi_N(x) \leq 1$ ,  $\psi_N(x) = 1$  on (1/N, 1 - 1/N), and  $0 \leq \psi(x) < 1$  on  $(0, 1/N) \cup (1 - 1/N, 1)$ . (See the Exercise below.) Then  $\psi_N \in \mathcal{D}(A)$  with  $A\psi_N(x) = L\psi_N(x)$ . By Lemma 5.2

$$Y_t^N(\omega) = \psi_N(X_t(\omega))I_{[\zeta(\omega)>t]} - \int_0^{t\wedge\zeta(\omega)} L\psi_N(X_s(\omega))ds$$
(7.4)

is a martingale. By the Optional Stopping Theorem

$$E_x\Big(Y_{t\wedge T_N}^N\Big) = E_x\Big(\psi_N\big(X_{t\wedge T_N}(\omega)\big)I_{[\zeta(\omega)>t\wedge T_N]}\Big) = \psi_N(x)$$
(7.5)

since  $A\psi_N(X_s) = L\psi_N(X_s) = 0$  for  $0 \le s < t \land T_N$ .

Let  $q_N(t,\omega)$  be the integrand in (7.5). Note that  $0 \leq t \wedge T_N \leq T_N$ . If  $T_N < \zeta$ , then  $\lim_{t\to\infty} q_N(t,\omega) = \tilde{\psi}_N = \psi_N(X_{T_N})$ . If  $T_N \geq \zeta$ , then  $\zeta(\omega) < \infty$  by (6.2) and  $\lim_{t\to\infty} q_N(t,\omega) = 0$ . In either case

$$\psi_N(x) = E_x \left( \widetilde{\psi}_N I_{[\zeta(\omega) > T_N]} \right)$$
(7.6)

where  $\tilde{\psi}_N = 0$  (for example) if  $T_N \geq \zeta$ . If 1/N < x < 1 - 1/N, then the expected value  $\psi_N(x) = 1$ . Since the integrand of (7.6) is bounded by one, it must be equal to one a.s. This implies  $P_x(\zeta(\omega) > T_N) = 1$ , which completes the proof of Theorem 7.1.

**Exercise.** Let  $k_N(x) = Nk(Nx)$  for

$$k(x) = \begin{cases} C \exp(-1/(1-x^2)) & \text{for } |x| < 1\\ 0 & \text{for } |x| \ge 1 \end{cases}$$

where C is chosen so that  $\int_{-\infty}^{\infty} k(y) dy = 1$ . Prove that (i) k(x) has continuous derivatives of all orders on the real line R (that is,  $k \in C^{\infty}(R)$ ) and (ii)  $\operatorname{Supp}(k) = [-1, 1]$ . Now set

$$\psi_N(x) = \int_{1/2N}^{1-1/2N} k_{2N}(x-y)dy$$

Prove that (iii)  $\psi_N(x)$  has continuous derivatives of all orders on R, (iv)  $0 \leq \psi_N(x) \leq 1$  for all x, (v)  $\psi_N(x) = 1$  for  $1/N \leq x \leq 1 - 1/N$ , and (vi)  $\psi_N(x) = 0$  if  $x \leq 0$  or  $x \geq 1$ .

**Remark.** It follows from (7.3) that

$$\max_{0 \le x \le 1} P_x(T_\infty \ge t_0) \le 1/2, \qquad t_0 = 2C \tag{7.7}$$

This implies by the Markov property and standard arguments that

Corollary 7.2. Under the assumptions of Theorem 7.1

$$\max_{0 \le x \le 1} P_x(T_\infty \ge t) \le 2e^{-\alpha t}, \quad t \ge 0$$
(7.8)

for  $\alpha = 2C \log 2 > 0$ , and also

$$\max_{0 \le x \le 1} E_x(e^{aT_{\infty}}) \le C_1(a), \quad 0 \le a < \alpha$$
(7.9)

where  $C_1(a) < \infty$  for  $0 \le a < \alpha$ .

We can use the same argument as in Theorem 7.1 to prove

**Theorem 7.2.** With probability one, the sample paths  $X_t(\omega)$  are continuous functions of t for  $0 \le t < \zeta(\omega)$ .

**Proof.** Since  $P_x(T_N < \zeta) = 1$  and  $E_x(\zeta) \leq C$ , it follows from (7.6) that  $\widetilde{\psi}_N = \psi_N(X_{T_N}) = 1$  a.s. in (7.6) for 1/N < x < 1 - 1/N. This implies that  $X_{T_N}(\omega) \in \{1/N, 1 - 1/N\}$  almost surely. This means that  $X_t(\omega)$  cannot leave (1/N, 1 - 1/N) by a jump beyond the boundary of (1/N, 1 - 1/N). This suggests that, at least,  $X_t(\omega)$  cannot be discontinuous at  $X_t(\omega) = 1/N$  or  $X_t(\omega) = 1 - 1/N$ .

If general, define

$$T_{ab}(\omega) = \min\{ t : t < \zeta(\omega), \ X_t(\omega) \in (0, a) \cup (b, 1) \}$$
(7.10)

for rational values a, b with 0 < a < b < 1 with, as before, the convention  $T_{ab}(\omega) = \infty$  if the set of t on the right-hand side of (7.10) is empty. By the same argument as in Theorem 7.1,  $P_x(T_{ab} < \infty) = 1$  and  $P_x(X_{T_{ab}} \in \{a, b\}) = 1$  for 0 < a < x < b < 1.

Expand the null set  $E \in \mathcal{F}$  in (4.7) to include the null set of all  $\omega \in \Omega$  that provide counterexamples to  $X_{T_{ab}(\omega)}(\omega) \in \{a, b\}$  for rational 0 < a < b < 1. It follows that, if  $\omega \notin E$ , there cannot exist any rational values r such that  $X_{t-}(\omega) < r < X_{t+}(\omega)$ , since we could then find a counterexample to  $X_{T_{ar}(\omega)}(\omega) \in \{a, r\}$  for some rational interval (a, r).

Similarly there cannot exist any rational values r such that  $X_{t+}(\omega) < r < X_{t-}(\omega)$  since we could find a counterexample to  $X_{T_{rb}(\omega)}(\omega) \in \{r, b\}$  for some rational interval (r, b). Since  $X_t(\omega)$  has at worst jump discontinuities for  $\omega \notin E$  by the argument that led up to (4.7), this implies that  $X_t(\omega)$  must be continuous in t for  $0 \le t < \zeta(\omega)$ . This completes the proof of Theorem 7.2.

8. Exit Times are Death Times. The purpose of this section is to prove that, in fact,  $T_{\infty}(\omega) = \zeta(\omega)$  almost surely for  $T_{\infty}(\omega) = \sup_{N} T_{N}(\omega)$ . We begin with two lemmas.

**Lemma 8.1.** If  $f, h \in C_0(I)$ , then  $h \in \mathcal{D}(A)$  and Ah = -f if and only if

$$h(x) = \int_0^1 g(x, y) f(y) m(dy)$$
(8.1)

**Proof.** If h(x) is given by (8.1), then  $h \in \mathcal{D}(A)$  and Ah = Lh = -f as in Section 1. Conversely, assume  $h \in \mathcal{D}(A)$  and Ah = -f. Define

$$h_1(x) = \int_0^1 g(x, y) f(y) m(dy)$$

Then  $h_1 \in \mathcal{D}(A)$  and  $Ah_1 = Lh_1 = -f$ . Let  $g = h - h_1$ . Then  $g \in \mathcal{D}(A)$  and  $Ag = Ah - Ah_1 = 0$ .

If  $g \in \mathcal{D}(A)$  and Ag = 0, it follows from Lemma 5.2 that  $g(X_t)I_{[\zeta > t]}$  is a uniformly-bounded martingale. Thus

$$g(x) = E_x(g(X_t)I_{[\zeta>t]})$$

By the relation  $P_x(T_N < \zeta) = 1$  and the Optional Stopping Theorem,

$$g(x) = E_x(g(X_{t \wedge T_N}))$$

Since  $P_x(T_N < \infty) = 1$  by Theorems 6.1 and 7.1 and g(x) is bounded, we can let  $t \to \infty$  and obtain

$$g(x) = E_x(g(X_{T_N}))$$

However,  $\lim_{N\to\infty} g(X_{T_N}) = 0$  since  $g \in C_0(I)$  by Corollary 7.1. This proves that g(x) = 0 for 0 < x < 1. Since  $g = h - h_1$ , it follows that  $h(x) = h_1(x) = \int g(x, y) f(y) m(dy)$ . This completes the proof of the lemma.

**Lemma 8.2.** For any  $f \in C_0(I)$  with  $f(x) \ge 0$ ,

$$\int_{0}^{1} g(x,y)f(y)m(dy) = \int_{0}^{\infty} T_{s}f(x)ds = E_{x}\left(\int_{0}^{\zeta(\omega)} f(X_{s})ds\right)$$
(8.2)

**Proof.** Define

$$h_{\lambda}(x) = R_{\lambda}f(x) = \int_{0}^{\infty} e^{-\lambda s} T_{s}f(x)ds$$

As in Section 2,  $h_{\lambda}(x) \in \mathcal{D}(A)$  and  $(\lambda I - A)h_{\lambda}(x) = f(x)$ . Thus  $Ah_{\lambda} = \lambda h_{\lambda} - f = -(f - \lambda h_{\lambda})$ . It then follows from Lemma 8.1 that

$$h_{\lambda}(x) = \int_{0}^{\infty} e^{-\lambda s} T_{s} f(x) ds = \int_{0}^{1} g(x, y) \big( f(y) - \lambda h_{\lambda}(y) \big) m(dy) \qquad (8.3)$$
$$\leq \int_{0}^{1} g(x, y) f(y) m(dy) \leq C \sup_{y} f(y)$$

since  $f(x) \ge 0$  and  $h_{\lambda}(y) \ge 0$ , where C is the constant in (2.7). Thus  $h_{\lambda}(x) \le C_1$  uniformly in  $\lambda > 0$ . Since then  $\lambda h_{\lambda}(x) \le C_1 \lambda$ , taking the limit  $\lambda \to 0$  in (8.3) for  $f(x) \ge 0$  implies

$$h_0(x) = \int_0^\infty T_s f(x) ds = \int_0^1 g(x, y) f(y) m(dy)$$
$$= E_x \left( \int_0^\infty f(X_s) I_{[\zeta > s]} ds \right) = E_x \left( \int_0^{\zeta(\omega)} f(X_s) ds \right)$$

This implies (8.2).

**Theorem 8.1.** Define  $T_N$ ,  $T_\infty$ , and  $\zeta$  as before. Then  $P_x(T_\infty = \zeta) = 1$  for all  $x \in I_0$ .

**Proof.** Let

$$h(x) = \int_0^1 g(x, y)\psi(y)m(dy)$$
(8.4)

for arbitrary  $\psi \in C_0(I)$  with  $\psi(y) \ge 0$ . Then  $Ah = -\psi$  and

$$Y_t(\omega) = h(X_t(\omega))I_{[\zeta(\omega)>t]} + \int_0^{t\wedge\zeta(\omega)} \psi(X_s(\omega))ds$$

is a nonnegative martingale by Lemma 5.2. Thus

$$E_x\Big(h(X_t)I_{[\zeta>t]} + \int_0^{t\wedge\zeta} \psi(X_s)ds\Big) = h(x)$$

for all  $t \ge 0$  and  $x \in I_0$ . By the Optional Stopping Theorem

$$h(x) = E_x \Big( h(X_{t \wedge T_N}) I_{[\zeta > t \wedge T_N]} + \int_0^{t \wedge T_N \wedge \zeta} \psi(X_s) ds \Big)$$
$$= E_x \Big( h(X_{t \wedge T_N}) + \int_0^{t \wedge T_N} \psi(X_s) ds \Big)$$

since  $P_x(T_N < \zeta) = 1$  by (7.2). Since h(x) is bounded,  $\psi(y) \ge 0$ , and  $T_N < \infty$  almost surely by (6.2), we can let  $t \to \infty$  and conclude

$$h(x) = E_x \Big( h(X_{T_N}) + \int_0^{T_N} \psi(X_s) ds \Big)$$
(8.5)

As  $N \to \infty$ ,  $h(X_{T_N}) \to 0$  since  $h \in C_0(I)$ . Since  $0 \leq T_N \uparrow T_\infty$  and  $\psi(X_s) \geq 0$ , we conclude from (8.5) that

$$h(x) = E_x \left( \int_0^{T_\infty(\omega)} \psi(X_s) ds \right)$$
(8.6)

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In contrast, by Lemma 8.2 and (8.4)

$$h(x) = E_x \left( \int_0^{\zeta(\omega)} \psi(X_s) ds \right)$$
(8.7)

Recall  $T_{\infty}(\omega) \leq \zeta(\omega)$  almost surely by (7.2). Both integrals in in (8.6) and (8.7) are finite since  $\psi(X_s) \geq 0$  and h(x) is finite. We can then subtract (8.6) from (8.7) to conclude

$$E_x\left(\int_{T_\infty(\omega)}^{\zeta(\omega)} \psi(X_s) ds\right) = 0$$

This holds for all  $\psi \in C_0(I)$  with  $\psi(x) \ge 0$ . We can approximate  $\psi(x) \equiv 1$ by nonnegative functions  $\psi_N \in C_0(I)$  by setting (for example)  $\psi_0(x) = 2\min\{x, 1-x\}$  and  $\psi_N(x) = \psi_0(x)^{1/N}$ . Then  $0 \le \psi_N(x) \le 1$  and  $0 \le \psi_N(x) \uparrow 1$  as  $N \to \infty$ . This implies

$$E_x(\zeta(\omega) - T_\infty(\omega)) = 0, \qquad T_\infty(\omega) \le \zeta(\omega) \text{ a.s.}$$
 (8.8)

Thus  $\zeta(\omega) - T_{\infty}(\omega) = 0$  almost surely with respect to  $P_x$  for all  $x \in I_0$ . This completes the proof of Theorem 8.1. (*Exercise:* Prove or disprove: (8.8) also holds for  $x = \Delta$ . Use the precise definitions of  $X_r(\omega)$ ,  $X_t(\omega)$ , and  $T_N(\omega)$ . Discuss.)

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