## Ma 309 — Matrix Algebra Solutions for Midterm Test #2

Prof. Sawyer — Washington Univ. — March 28, 2007

**1.** Using elementary row operations:

$$A = \begin{bmatrix} 2 & 3 & 7 & 4 \\ 1 & 2 & 4 & 2 \\ -1 & 1 & 5 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 5 & 17 & 12 \\ 0 & 3 & 9 & 6 \\ -1 & 1 & 5 & 4 \end{bmatrix}$$
$$\rightarrow \begin{bmatrix} 1 & -1 & -5 & -4 \\ 0 & 1 & 3 & 2 \\ 0 & 5 & 17 & 12 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & -2 & -2 \\ 0 & 1 & 3 & 2 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

after dividing the last row by 2. Since each row has a leading 1,  $\operatorname{rank}(A) = 3$ .

**2.** (a) Since x and y are  $n \times 1$  column vectors,  $x^T$  and  $y^T$  are  $1 \times n$  row vectors. Thus  $xy^T$  is  $(n \times 1) \times (1 \times n) = n \times n$  and  $x^T y$  is  $(1 \times n) \times (n \times 1) = 1 \times 1$ . In fact,  $x^T y$  is the number  $\sum_{i=1}^n x_i y_i$ .

(b) By matrix multiplication,

$$xy^{T} = \begin{bmatrix} x_{1} \\ x_{2} \\ \dots \\ x_{n} \end{bmatrix} \begin{bmatrix} y_{1} \ y_{2} \ \dots \ y_{n} \end{bmatrix} = \begin{bmatrix} x_{1}y_{1} \ x_{1}y_{2} \ \dots \ x_{1}y_{n} \\ x_{2}y_{1} \ x_{2}y_{2} \ \dots \ x_{2}y_{n} \\ \dots \ \dots \ \dots \\ x_{n}y_{1} \ x_{n}y_{2} \ \dots \ x_{n}y_{n} \end{bmatrix}$$

If  $A = xy^T$ , then  $A_{ij} = (xy^T)_{ij} = x_i y_j$ . Thus  $tr(A) = tr(xy^T) = \sum_{i=1}^n a_{ii} = \sum_{i=1}^n x_i y_i = x^T y$ .

**3.** Here  $W = \{x \text{ in } R^4 : x_1 - x_4 = x_2 - x_3\}$  where  $x_1, x_2, x_3, x_4$  are the components of x.

(a) Proof #1: The condition on  $x = [x_1 \ x_2 \ x_3 \ x_4]^T$  to be in W is linear. One can then check that if x, y are in W, then the components of cx and x + y satisfy the relation to be in W, so that cx, x + y are in W as well. This means that W is a vector subpace of  $\mathbb{R}^4$ . Proof #2: If x satisfies the relation to be in W, then

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} x_2 - x_3 + x_4 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$
$$= x_2 v_1 + x_3 v_2 + x_4 v_3$$

where  $x_2, x_3, x_4$  are arbitrary and  $v_1, v_2, v_3$  are the three vectors on the right on the first line. Thus  $W = \operatorname{span}\{v_1, v_2, v_3\}$ . Since the vector span of any set of vectors is automatically a vector space, W is a vector space. (b) It is easy to check that the vectors  $v_1, v_2, v_3$  above are linearly inde-

- pendent. Since they span W, they form a basis for W.
- (c) Since W has a basis composed of 3 vectors,  $\dim(W) = 3$ .

4. Here  $x = \sum_{i=1}^{n} c_i w_i = \sum_{j=1}^{n} c_j w_j$  where  $w_1, w_2, \ldots, w_n$  are orthogonal nonzero vectors with respect to an inner product (u, v). This means that

$$(x, w_i) = \left(\sum_{j=1}^n c_j w_j, w_i\right) = \sum_{j=1}^n c_j (w_j, w_i) = c_i(w_i, w_i)$$

since  $(w_i, w_j) = 0$  for  $j \neq i$ . Since  $(w_i, w_i) > 0$  since  $w_i$  is nonzero, this implies  $c_i = (x, w_i)/(w_i, w_i)$ .

**5.** (This was the hardest question.)

Proof #1: If  $(u, v)_0 = \sum_{i=1}^n u_i v_i$  is the usual inner product in  $\mathbb{R}^n$ , then  $(Cu, v)_0 = (u, C^T v)_0$  for any  $n \times n$  matrix C. This is in the text: A short proof is

$$(Cu, v)_0 = \sum_{i=1}^n (Cu)_i v_i = \sum_{i=1}^n \left(\sum_{k=1}^n C_{ik} u_k\right) v_i = \sum_{i=1}^n \sum_{k=1}^n C_{ik} u_k v_i$$
$$= \sum_{k=1}^n u_k \sum_{i=1}^n C_{ik} v_i = \sum_{k=1}^n u_k \sum_{i=1}^n (C^T)_{ki} v_i = (u, C^T v)_0$$

By definition,  $(u, v)_A = (u, Av)_0$ . Thus

$$(Bu, v)_A = (Bu, Av)_0 = (Bu, (Av))_0 = (u, B^T Av)_0$$
  
 $(u, Bv)_A = (u, (Bv))_A = (u, A(Bv))_0 = (u, ABv)_0$ 

Hence if  $AB = B^T A$ , then  $(Bu, v)_A = (u, Bv)_A$ . (Note that a hint is not mandatory! There are other short proofs that do not involve expanding  $(Bu, v)_A$  as a triple sum as in the second proof.)

Proof #2: Note

$$(Bu, v)_{A} = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij} (Bu)_{i} v_{j} = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij} \sum_{k=1}^{n} B_{ik} u_{k} v_{j}$$
$$(u, Bv)_{A} = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij} u_{i} (Bv)_{j} = \sum_{i=1}^{n} \sum_{j=1}^{n} A_{ij} u_{i} \sum_{k=1}^{n} B_{jk} v_{k}$$

The key is that you get two triple sums, not double sums. Note also

$$\sum_{i=1}^{n} A_{ij} B_{ik} = \sum_{i=1}^{n} (B^T)_{ki} A_{ij} = (B^T A)_{kj}$$
$$\sum_{j=1}^{n} A_{ij} B_{jk} = (AB)_{ik}$$

Thus by summing over i in the first triple sum and over j in the second triple sum,

$$(Bu, v)_A = \sum_{j=1}^n \sum_{k=1}^n (B^T A)_{kj} u_k v_j = \sum_{j=1}^n \sum_{i=1}^n (B^T A)_{ij} u_i v_j$$
$$(u, Bv)_A = \sum_{i=1}^n \sum_{k=1}^n (AB)_{ik} u_i v_k = \sum_{i=1}^n \sum_{j=1}^n (AB)_{ij} u_i v_j$$

The two final sums are the same if  $AB = B^T A$ .

**6.** If  $V = \text{span}\{v_1, v_2\}$ , then x in  $V^{\perp}$  if and only if  $(x, v_1) = (x, v_2) = 0$  for  $x = [x_1 \ x_2 \ x_3]^T$ .

Proof #1: This is equivalent to two equations in three unknowns:

$$\begin{aligned} x_1 + 2x_2 + 4x_3 &= 0\\ 3x_1 + x_2 + 7x_3 &= 0 \end{aligned}$$
(1)

By elementary row operations

$$\begin{bmatrix} 1 & 2 & 4 \\ 3 & 1 & 7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & -5 & -5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$

This means that the system (1) is equivalent to the system

$$x_1 + 2x_3 = 0$$
$$x_2 + x_3 = 0$$

This in turn is equivalent to

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2x_3 \\ -x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} = -x_3 \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$$

with no constraints on  $x_3$ . This means that  $\{ \begin{bmatrix} -2 & -1 & 1 \end{bmatrix}^T \}$  is a basis for  $V^{\perp}$ .

Proof #2: A few people tried the following approach: (i) Use Gram-Schmidt orthogonalization to convert  $\{v_1, v_2\}$  to an orthogonal basis  $\{v_1, w_2\}$  for V where  $w_2 = v_2 - cv_1$ . Then (ii) use Gram-Schmidt orthogonalization again to extend  $\{v_1, w_2\}$  to an orthogonal basis  $\{v_1, w_2, w_3\}$  for all of  $R^3$ . Then one must have  $V^{\perp} = \operatorname{span}\{w_3\}$ , so that  $\{w_3\}$  is a basis for  $V^{\perp}$ .

This approach is OK, but is computationally more difficult. It is not difficult to find  $w_2$  with integer entries, but no one was able to push through the argument to find  $w_3$  (which by the first proof would have to be a constant times  $\begin{bmatrix} 2 & 1 & -1 \end{bmatrix}^T$ ).