

2. (a) For which real number  $k$  is the following matrix invertible?

$$A = \begin{pmatrix} 1 & 1 & 0 & 0 & 1 \\ -1 & k & 0 & 0 & 0 \\ 0 & 0 & 1 & 3 & 9 \\ 0 & 0 & 1 & 4 & 16 \\ 0 & 0 & 1 & k & k^2 \end{pmatrix}$$

[5 points]

$$\begin{aligned} \det(A) &= \det \begin{pmatrix} 1 & 1 \\ -1 & k \end{pmatrix} \det \begin{pmatrix} 1 & 3 & 9 \\ 1 & 4 & 16 \\ 1 & k & k^2 \end{pmatrix} \\ &= (k+1)(k^2-7k+12) \\ &= (k+1)(k-3)(k-4) \end{aligned}$$

Therefore,  $\det(A) = 0 \Leftrightarrow k = 3, 4, -1$   
 so  $A$  is invertible for every  $k \neq 3, 4, -1$ .

(b) Suppose

$$\begin{pmatrix} 4 & 1 & 10 \\ 2 & -2 & 17 \\ -2 & 4 & 14 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}$$

Use Cramer's rule to find  $x_2$ .

[3 points]

$B_2 = \begin{pmatrix} 4 & 2 & 10 \\ 2 & 1 & 17 \\ -2 & -1 & 14 \end{pmatrix}$ . Since the second column of  $B_2$  is a multiple of its first column,  $\det B_2 = 0$ .  
 We have  $x_2 = \frac{\det(B_2)}{\det(A)_3} = 0$ .

3. Let  $A = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix}$  and  $B = \begin{pmatrix} -1 & 0 \\ 3 & 1 \end{pmatrix}$ . Determine the matrix of the linear transformation

$$T: F^{2 \times 2} \rightarrow F^{2 \times 2}$$

defined by

$$T(M) = AMB$$

with respect to the basis  $\mathcal{B} = \{E_{1,1}^{1,1}, E_{1,2}^{1,1}, E_{1,1}^{2,1}, E_{1,2}^{2,1}\}$ .

( $E^{i,j}$  is the matrix which has 1 in the  $ij$ -th entry and 0 elsewhere).

[6 points]

We have

$$T(E_{1,1}^{1,1}) = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix}$$

$$T(E_{1,2}^{1,1}) = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 3 & 1 \end{pmatrix}$$

$$T(E_{1,1}^{2,1}) = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ -2 & 0 \end{pmatrix}$$

$$T(E_{1,2}^{2,1}) = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 3 & 1 \end{pmatrix} = \begin{pmatrix} 3 & 1 \\ 6 & 2 \end{pmatrix}$$

Therefore

$$[T]_{\mathcal{B}} = \begin{pmatrix} 0 & 0 & -1 & 3 \\ 0 & 0 & 0 & 1 \\ -1 & 3 & -2 & 6 \\ 0 & 1 & 0 & 2 \end{pmatrix}$$

4. The *dot product* of two vectors  $\alpha$  and  $\beta$  in  $F^{n \times 1}$  is defined as follows: if  $\alpha = \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix}$

and  $\beta = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$ , then

$$\alpha \cdot \beta = a_1 b_1 + \cdots + a_n b_n.$$

If  $A$  is a matrix with column vectors  $\alpha_1, \dots, \alpha_n$ , then show that

$$(\det A)^2 = \det \begin{pmatrix} \alpha_1 \cdot \alpha_1 & \alpha_1 \cdot \alpha_2 & \cdots & \alpha_1 \cdot \alpha_n \\ \alpha_2 \cdot \alpha_1 & \alpha_2 \cdot \alpha_2 & \cdots & \alpha_2 \cdot \alpha_n \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_n \cdot \alpha_1 & \alpha_n \cdot \alpha_2 & \cdots & \alpha_n \cdot \alpha_n \end{pmatrix}$$

[5 points]

We have  $\alpha \cdot \beta = \alpha^T \beta$ .

So

$$\det \begin{pmatrix} \alpha_1 \cdot \alpha_1 & \cdots & \alpha_1 \cdot \alpha_n \\ \vdots & \ddots & \vdots \\ \alpha_n \cdot \alpha_1 & \cdots & \alpha_n \cdot \alpha_n \end{pmatrix} = \det \left[ \begin{pmatrix} \alpha_1^T \\ \vdots \\ \alpha_n^T \end{pmatrix} \begin{pmatrix} \alpha_1 & \alpha_2 & \cdots & \alpha_n \end{pmatrix} \right]$$

$$= \det(A^T A) = \det(A^T) \det(A) = \det(A) \det(A) = \det(A)^2.$$

5. Label the following statements as TRUE or FALSE, giving a short explanation (e.g. a proof or counterexample). [13 points]

- (a) If  $W$  is a proper subspace of a finite-dimensional vector space  $V$  (i.e.  $W \neq V$ ), then there is a non-zero linear functional  $f \in V^*$  such that  $f$  is zero on each vector in  $W$ .

True: Since  $W \neq V$ ,  $W^\circ \neq V^\circ = \{0\}$   
 $\Rightarrow$  there is  $0 \neq f \in W^\circ \subset V^*$ .

- (b) The function  $D : F^{3 \times 3} \rightarrow F$  define by

$$D\left(\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}\right) = a_{12}a_{21}a_{23}$$

is a 3-linear function.

False.  $D\left(\begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}\right) + D\left(\begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}\right)$   
 $= a_{11}a_{21}a_{23} + a_{11}a_{21}a_{23} = 2a_{11}a_{21}a_{23}$   
 $\neq D\left(\begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 + \alpha_3 \end{pmatrix}\right) = a_{11}a_{21}a_{23}$

- (c) If  $T : V \rightarrow W$  is a linear transformation between finite-dimensional vector spaces and  $T^t$  denote the transpose of  $T$ , then  $T$  is one-one if and only if  $T^t$  is onto.

True:  $T$  is one-one  $\Leftrightarrow$  nullity  $(T) = 0$   
 $\Leftrightarrow$  rank  $(T) = \dim V$   
 $\Leftrightarrow$  rank  $(T^t) = \dim V$   
 $\Leftrightarrow T^t$  is onto.

- (d) If  $\mathcal{B} = \{\epsilon_1, \epsilon_2, \epsilon_3\}$  is the standard basis for  $\mathbf{R}^3$  and  $\mathcal{B}' = \{\epsilon_1, \epsilon_2 - \epsilon_1, \epsilon_3 - \epsilon_2\}$ , then the matrix of change of coordinates from  $\mathcal{B}'$  to  $\mathcal{B}$  is

$$\begin{pmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}.$$

False: The matrix of change of coordinates from  $\mathcal{B}'$  to  $\mathcal{B}$  is

$$\begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix}.$$

- (e) If  $V$  is a 3-dimensional vector space,  $\mathcal{B} = \{\alpha_1, \alpha_2, \alpha_3\}$  a basis for  $V$ , and  $f_1, f_2, f_3$  the corresponding dual basis for  $V^*$ , then

$$f_1, 2f_2, 3f_3$$

is the dual basis corresponding to the basis

$$\mathcal{B}' = \{\alpha_1, 2\alpha_2, 3\alpha_3\}.$$

False:  $2f_2(2\alpha_2) = 4f_2(\alpha_2) = 4 \neq 1$ .