

Final Examination
Math 441, Fall 2003

There is a total of 100 points.

Define the following (7 points each):

1. A Riemannian metric on a differentiable manifold M^n .
2. The Frobenius condition for a smooth k -plane distribution \mathcal{D} on a smooth manifold M^n .
3. A Lie group G .

Prove the following form of the Gauss-Bonnet Theorem (30 points).

4. Let M^2 be an oriented Riemannian surface with Gaussian curvature K and area element dA . If T is a geodesic triangle, then

$$\int_T K dA = \sum_{i=1}^3 \alpha_i - \pi$$

where α_i is the interior angle at the i^{th} vertex of T . You may assume that your version of Stokes's Theorem applies to T and that T lies in an open set U on which there is an oriented orthonormal moving frame e_1, e_2 .

Do the following problems (worth 7 points each).

5. Let α be a closed differentiable k -form and let β be an exact differentiable r -form, on a differentiable manifold M^n . Prove that $\alpha \wedge \beta$ is exact.
6. Prove that a closed 1-form α on the sphere $S^n \subset \mathbf{R}^{n+1}$ is exact, if $n \geq 2$.

(Continued on back of the page)

Let $\gamma : J \rightarrow \mathbf{R}^3$ be a smooth embedded curve in \mathbf{R}^3 parametrized by arclength parameter $s \in J$, where J is an interval containing 0. Assume that the curvature $\kappa(s)$ is positive for every point $s \in J$. Let $T = \dot{\gamma}$, N , B be its Frenet frame, with Frenet-Serret equations

$$\dot{T} = \kappa N, \quad \dot{N} = -\kappa T + \tau B, \quad \dot{B} = -\tau N$$

where the function $\tau(s)$ is the torsion.

Let r be a positive constant such that $r < 1/\kappa(s)$ for all $s \in J$. The *tube* around γ of radius r is the map

$$\begin{aligned} \mathbf{x} : J \times \mathbf{R} &\rightarrow \mathbf{R}^3 \\ \mathbf{x}(s, t) &= \gamma(s) + r(\cos t N(s) + \sin t B(s)) \end{aligned}$$

7. Prove that \mathbf{x} is an immersion on $M = J \times \mathbf{R}$.
8. Prove that $e_3(s, t) = \cos t N(s) + \sin t B(s)$ is a Gauss map of \mathbf{x} .
9. For the orthonormal moving frame

$$e_1(s, t) = T(s), \quad e_2(s, t) = \sin t N(s) - \cos t B(s), \quad e_3(s, t)$$

find the dual coframe field θ^1, θ^2 and its Levi-Civita connection form $\omega_2^1 = -\omega_1^2$.

10. Find the second fundamental form

$$II = h_{11}\theta^1\theta^1 + 2h_{12}\theta^1\theta^2 + h_{22}\theta^2\theta^2$$

of \mathbf{x} for the Gauss map e_3 .

11. If $L > 0$ and $L \in J$, find the area of $\mathbf{x}(D)$, where $D = [0, L] \times [0, 2\pi] \subset M$.