## Final Examination Math 441, Fall 2004

You may use theorems from advanced calculus, such as the inverse and implicit function theorems and the rank theorem, by citation without proof.

- 1). Define the real projective space  $P^n(\mathbf{R})$  (as a topological manifold) and prove that it is compact.
- 2). Prove that if  $f_1, \ldots, f_n$  are  $C^{\infty}$  functions on a  $C^{\infty}$  manifold  $M^n$  such that

$$df_1(p) \wedge \cdots \wedge df_n(p) \neq 0$$

at some point  $p \in M$ , then there exists a chart U, x about p for which  $x^i = f_i$  restricted to U. Hint: consider  $F = (f_1, \ldots, f_n) : M \to \mathbf{R}^n$ .

- 3). Let  $\theta: W \subset \mathbf{R} \times S^2 \to S^2$  be the flow of the  $C^{\infty}$  vector field X(x, y, z) = (0, z, -y) on the unit sphere  $S^2$ .
  - i). Find W.
  - ii). Find  $\theta(t, (1, 0, 0))$ , for every  $t \in \mathbf{R}$  at which it is defined.
- 4). On  $\mathbb{R}^3$  consider the 2-plane distribution  $\mathcal{D}^{\perp} = \{\alpha\}$ , where

$$\alpha = dx + zdy - xdz$$

and where x, y, z are the standard coordinates on  $\mathbf{R}^3$ . Verify whether this distribution is involutive.

5). Let  $U_1$  and  $U_2$  be open subsets of the  $C^{\infty}$  manifold  $M^n$ . Let k be an integer between 0 and n. The Mayer-Vietoris sequence is based on the short exact sequence of cochains

$$0 \to A^k(U_1 \cup U_2) \xrightarrow{i} A^k(U_1) \oplus A^k(U_2) \xrightarrow{j} A^k(U_1 \cap U_2) \to 0$$

Explain how j is defined and use a partition of unity to prove that it is onto.

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- 6). Let  $F: G \to H$  be a Lie group homomorphism between the Lie groups G and H. Let X be a left-invariant vector field on G and let Y be the left-invariant vector field on H determined by the vector  $dF_{(e)}X_{(e)} \in T_eH$ . Prove that Y is F-related to X.
- 7). Let  $S^2$  be the unit sphere in  $\mathbf{R}^3$ , let  $j: S^2 \hookrightarrow \mathbf{R}^3$  be the inclusion map, and let  $M^2 = \{p \in S^2 : z(p) \geq 0\}$  be the closed northern hemisphere. Let  $S^2$  have the orientation defined by the nowhere vanishing 2-form  $j^*(\iota_{(x,y,z)}dx \wedge dy \wedge dz)$ , where x, y, z are the standard coordinates on  $\mathbf{R}^3$ .
- i). State Stokes's Theorem for the 1-form  $\alpha = j^*(xdy ydz)$  on M. Explain the correct orientation on the boundary of M.
  - ii). Calculate  $\int_{\partial M} \alpha$ , where  $\partial M$  has the induced orientation.