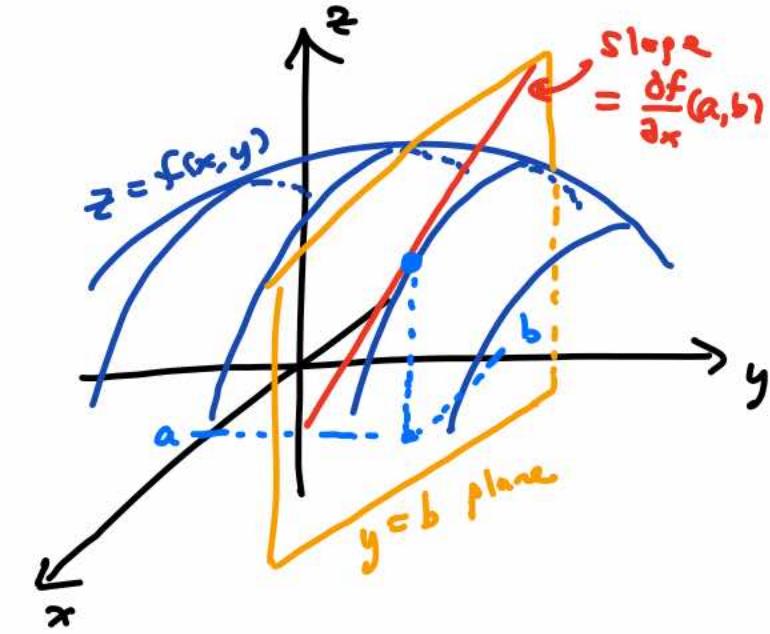


Lecture 26 : Partial Derivatives

Given a function $f: \mathcal{S} \rightarrow \mathbb{R}$ defined on a set $\mathcal{S} \subseteq \mathbb{R}^n$, the idea of partial derivatives is to hold all variables but one — say, x_k — constant, and differentiate with respect to x_k to get " $\frac{\partial f}{\partial x_k}$ " or " $D_{k,f}$ ". If $n=2$, we often write (x,y) instead of $\vec{x} = (x_1, x_2)$ and the geometric idea is to slice the graph $z = f(x,y)$ by the plane $y=b$, then compute the slope of $z = f(x,b)$ at $x=a$:

$$\frac{\partial f}{\partial x}(a,b) := \lim_{h \rightarrow 0} \frac{f(a+h,b) - f(a,b)}{h}.$$



More generally, $\frac{\partial f}{\partial x} := \lim_{h \rightarrow 0} \frac{f(x+h,y) - f(x,y)}{h}$ & $\frac{\partial f}{\partial y} := \lim_{h \rightarrow 0} \frac{f(x,y+h) - f(x,y)}{h}$.

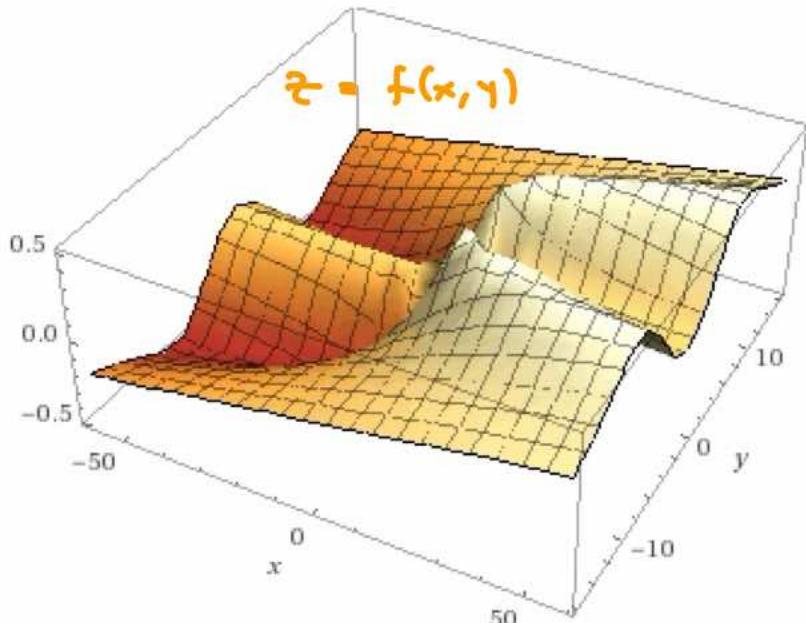
Ex 1/ $f(x,y) = \sin\left(\frac{x}{1+y}\right) \rightsquigarrow \frac{\partial f}{\partial x} = \frac{1}{1+y} \cos\left(\frac{x}{1+y}\right)$ and

$$\frac{\partial f}{\partial y} = \left(\frac{\partial}{\partial y} \frac{x}{1+y} \right) \cos\left(\frac{x}{1+y}\right) = \frac{-x}{(1+y)^2} \cos\left(\frac{x}{1+y}\right).$$

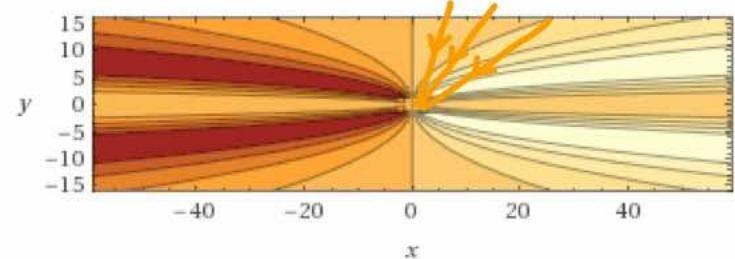
Ex 2/ $f(x,y) := \begin{cases} \frac{xy^2}{x^2+y^4}, & (x,y) \neq (0,0) \\ 0, & (x,y) = (0,0) \end{cases}$ We showed last

time that this was not continuous at $(0,0)$ (because limits along paths $x=y^2$ and $y=mx$ disagree). But the

partials do exist : restricting to $y=0$ and differentiating w.r.t. x gives $\frac{\partial f}{\partial x}(0,0) = \frac{\partial}{\partial x} f(x,0) \Big|_{x=0} = \frac{d}{dx} 0 \Big|_{x=0} = 0$;
 and restricting to $x=0$ etc. gives $\frac{\partial f}{\partial y}(0,0) = \frac{\partial}{\partial y} f(0,y) \Big|_{y=0} = \frac{d}{dy} 0 = 0$.



The graph



Contour plot
(level curves)

- I have drawn a few of the linear paths into $(0,0)$ that gave $\lim = 0$. //

There are essentially 3 cases to consider :

- partials exist and are continuous at $(a,b) \Rightarrow z = f(x,y)$ is well-approximated by a "tangent plane" at $(a,b, f(a,b))$
- partials don't exist at $(a,b) \Rightarrow$ something like  or 
- partials exist but are not continuous at (a,b)
 - the weird in-between case we find ourselves in above (Ex. 2)

We don't consider $f(x,y)$ "differentiable" at (a,b) in the 2nd or 3rd case.

Having done the overview, let's turn to definitions, again in the general case of $\mathbb{R}^n \ni \vec{x} \xrightarrow{f} \mathbb{R}$, with $\vec{a} \in \text{int}(\mathcal{S})$.

Differentiation with respect to a vector $\vec{y} \in \mathbb{R}^n$:

$$f'(\vec{a}; \vec{y}) := \lim_{h \rightarrow 0} \frac{f(\vec{a} + h\vec{y}) - f(\vec{a})}{h}$$

- $f'(\vec{a}; \vec{0}) = 0$
- $f(\vec{x}) = \vec{\lambda} \cdot \vec{x}$ linear $\Rightarrow f'(\vec{a}; \vec{y}) = \lim_{h \rightarrow 0} \frac{f(\vec{a} + h\vec{y}) - f(\vec{a})}{h} = f(\vec{y})$.
- $g(t) := f(\vec{a} + t\vec{y}) \Rightarrow g'(t) = f'(\vec{a} + t\vec{y}; \vec{y})$
(e.g. if $f(\vec{x}) = \|\vec{x}\|^2 = \vec{x} \cdot \vec{x}$, $f'(\vec{a}; \vec{y}) = g'(0) = \frac{d}{dt} (\vec{a} + t\vec{y}) \cdot (\vec{a} + t\vec{y}) \Big|_{t=0} = 2\vec{a} \cdot \vec{y}$)
- Mean-value theorem for $g(t)$ on $[0, 1] \Rightarrow f(\vec{a} + \vec{y}) - f(\vec{a}) = f'(\vec{a} + t_0\vec{y}; \vec{y})$ for some $t_0 \in (0, 1)$.
- This is called the directional derivative $D_{\vec{u}} f$ if $\vec{y} = \vec{u}$ is a unit vector
- partial derivatives $\frac{\partial f}{\partial x_k} = D_{\vec{e}_k} f(\vec{a}) := D_{\vec{e}_k} f(\vec{a}) = \lim_{h \rightarrow 0} \frac{f(\vec{a} + h\vec{e}_k) - f(\vec{a})}{h}$ are a special case of directional derivatives

E x 3 / f as in Ex. 2, $\vec{y} = (\alpha, \beta)$, $\vec{a} = (0, 0)$

$$g(t) = f(\alpha t, \beta t) = \frac{\alpha \beta^2 t}{\alpha^2 + \beta^4 t^2}$$

$$\Rightarrow f'(0; \vec{y}) = g'(0) = \left. \frac{(\alpha^2 \beta^4 t^2) \alpha \beta^2 - \alpha \beta^4 t (2\beta^4 t)}{(\alpha^2 + \beta^4 t^2)^2} \right|_{t=0} = \frac{\beta^2}{\alpha} \quad \text{if } \alpha \neq 0$$

not both 0

(or 0 if $\alpha = 0$, since then $g(t) \equiv 0$)

\Rightarrow all the directional derivatives exist at $(0, 0)$

$$\|\vec{y}\| = 1 \Rightarrow \alpha^2 + \beta^2 = 1, \text{ or rather } \alpha = \cos \theta, \beta = \sin \theta$$

with value $\frac{\sin^2 \theta}{\cos \theta}$ if $\cos \theta \neq 0$, and 0 (!) if $\cos \theta = 0$. //

Total derivative of f at \vec{a} :

This is a linear transformation $T_{\vec{a}} : \mathbb{R}^n \rightarrow \mathbb{R}$ such that

$$E(\vec{a}; \vec{h}) := \frac{f(\vec{a} + \vec{h}) - f(\vec{a}) - T_{\vec{a}}(\vec{h})}{\|\vec{h}\|} \rightarrow 0 \text{ as } \|\vec{h}\| \rightarrow 0.$$

If it exists, then f is differentiable at \vec{a} .

- Theorem: If f is differentiable at \vec{a} , then

(a) the partial derivatives exist and $T_{\vec{a}}(\vec{y}) = \sum_{k=1}^n \left(\frac{\partial f}{\partial x_k}(\vec{a}) \right) y_k$

(b) the derivatives w.r.t. \vec{y} exist and are $f'(\vec{a}; \vec{y}) = T_{\vec{a}}(\vec{y})$.

Proof: $f'(\vec{a}; \vec{y}) = \lim_{h \rightarrow 0} \frac{f(\vec{a} + h\vec{y}) - f(\vec{a})}{h} = h T_{\vec{a}}(\vec{y}) \text{ by linearity}$

$$\begin{aligned} h &= h\vec{y} \rightarrow \\ &= \lim_{h \rightarrow 0} \frac{\|h\| \|\vec{y}\| E(\vec{a}; \vec{h}) + T_{\vec{a}}(h\vec{y})}{h} \\ &= \lim_{h \rightarrow 0} \frac{\|h\| \|\vec{y}\| \underbrace{E(\vec{a}; \vec{h})}_{\rightarrow 0} + T_{\vec{a}}(h\vec{y})}{h} \\ &= T_{\vec{a}}(\vec{y}). \end{aligned}$$

Since $T_{\vec{a}}$ is linear, any $\vec{y} = \sum y_k \vec{e}_k$, we set

$$T_{\vec{a}}(\vec{y}) = \sum_k y_k T_{\vec{a}}(\vec{e}_k) = \sum_k y_k f'(\vec{a}; \vec{e}_k) = \sum_k y_k \frac{\partial f}{\partial x_k}(\vec{a}). \quad \square$$

Ex 4/ Revisiting the function from Ex. 2 yet again,

notice that since $f'(\vec{0}; \vec{y}) = \begin{cases} y_2/y_1, & y_1 \neq 0 \\ 0, & y_1 = 0 \end{cases}$

is nonlinear in \vec{y} , f is not differentiable at $\vec{0}$ (even though its partial derivatives exist!). //

- Gradients: $\vec{\nabla} f := \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right)$ is a function from $\mathbb{R}^n \times \mathcal{S} \rightarrow \mathbb{R}^n$, i.e. a "vector field". Notice that

$$T_{\vec{a}}(\vec{y}) = \sum_{k=1}^n \frac{\partial f}{\partial x_k}(\vec{a}) \vec{y}_k = (\vec{\nabla} f(\vec{a})) \cdot \vec{y} \text{ or } \underbrace{(\vec{\nabla} f(\vec{a}))}_{\text{linear transformation}} \vec{y},$$
 which is consistent with a linear transformation from $\mathbb{R}^n \rightarrow \mathbb{R}$ being given by a $1 \times n$ matrix.
- Gradients of directional derivatives: gives a unit vector \vec{u} ,

$$(D_{\vec{u}} f)(\vec{a}) = f'(\vec{a}; \vec{u}) = T_{\vec{a}}(\vec{u}) = \vec{\nabla} f(\vec{a}) \cdot \vec{u} = \|\vec{\nabla} f(\vec{a})\| \cos \theta$$
 where θ is the angle between $\vec{\nabla} f(\vec{a})$ and \vec{u} .
- Differentiability \rightarrow Continuity (of course, converse is false)

Proof: $0 \leq |f(\vec{a} + \vec{h}) - f(\vec{a})| = |\vec{\nabla} f(\vec{a}) \cdot \vec{h} + \|\vec{h}\| E(\vec{a}; \vec{h})|$

*by triangle inequality
+ Cauchy-Schwarz*

$$\leq \|\vec{\nabla} f(\vec{a})\| \|\vec{h}\| + \|\vec{h}\| |E(\vec{a}, \vec{h})| \xrightarrow{\text{as } \|\vec{h}\| \rightarrow 0} 0 \quad \square$$

- Theorem: If $\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}$ exist in a ball about \vec{a} and are continuous at \vec{a} , then f is differentiable at \vec{a} .

Proof: (WLOG $\vec{a} = \vec{0}$) We need to show that

$$(*) \quad \frac{f(\vec{h}) - f(\vec{0}) - \vec{\nabla} f(\vec{0}) \cdot \vec{h}}{\|\vec{h}\|} \rightarrow 0 \quad \text{as } \|\vec{h}\| \rightarrow 0.$$

Write $\vec{h} = h\vec{u}$, \vec{u} = unit vector, $\vec{v}_k = \sum_{j=1}^k u_j \vec{e}_j$

$\Rightarrow f(h\vec{u}) - f(\vec{0}) = \sum_{k=1}^n \{f(h\vec{v}_k) - f(h\vec{v}_{k-1})\} = \sum_{k=1}^n h u_k \frac{\partial f}{\partial x_k}(\vec{c}_k)$

$= h \sum_{k=1}^n u_k \frac{\partial f}{\partial x_k}(\vec{c}_k)$

on segment connecting
 $h\vec{v}_{k-1}$ & $h\vec{v}_k$
MVT
from above

$$\text{So } G^*(\vec{x}) \text{ becomes } \frac{h \left\{ \sum_{k=1}^n \left(\frac{\partial f}{\partial x_k}(\vec{c}_h) - \frac{\partial f}{\partial x_k}(\vec{0}) \right) \right\}}{h \cancel{\rightarrow 0}},$$

which goes to zero by continuity of the $\frac{\partial f}{\partial x_k}$'s — since $h \rightarrow 0$ forces $\vec{c}_h \rightarrow \vec{0}$. □

For the function of Examples 2-4, while its partial derivatives exist, they clearly can't be continuous at $\vec{0}$. Which makes sense, b/c the function itself isn't continuous!