1. Consider the ODE

$$P'(t) = P(P-1)(5-P).$$

Sketch solutions for different initial conditions. What are the fixed points? Which are attracting and which are repelling? If this modeled a biological population, what are the qualitative features of the model.

- 2. For both of the next two equations, sketch the vector field (as in Example 2.8.1 in Strogatz), find all the fixed points, classify their stability, and sketch the graph of x for different initial conditions.
 - (i) $\dot{x} = 1 + \frac{1}{2}\cos(x)$
 - (i) $\dot{x} = 1 + 2\cos(x)$
 - 3. Do problem 2.2.8
 - 4. Do problem 2.2.9

Computer Exercises

You need to learn to use a program that solves ODE's. There are several, such as Mathematica and Matlab. I will give explicit instructions for Octave, which is free, but you may use other packages if you prefer. The purpose of the next 2 exercises is just to get a package installed and to run it with simple examples. Play around with parameters (like the number of t-values) to see what happens.

C1. Plot solutions of the ODE from exercise 1 numerically.

Here is one way to do it in Octave GUI.

Have a function file called LogThresh.m. (Notice it must have the same name as the function). It would contain the following:

```
function xdot = LogThresh(x,t)

c1 = 1;

c2 = 5;

xdot = x*(x-c1)*(c2-x);

endfunction
```

Now have a command file called RunLogThresh.m, containing

```
 \begin{aligned} &x1 = 1.19; \\ &t=linspace(0,3,100)'; \\ &x=lsode("LogThresh",x1,t); \\ &plot(t,x) \end{aligned}
```

Alternatively, you could enter all these lines on a command window; the advantage of saving scripts is it is easier to modify them.

C2. Consider the pendulum equation

$$\ddot{\theta} = -\sin(\theta).$$

Solve this with initial conditions $\theta(0) = 0, \dot{\theta}(0) = 1.99$ and $\theta(0) = 0, \dot{\theta}(0) = 2.01$. What is the qualitative difference?

Here is my Octave code. Now x is a 2-dimensional vector, with $x(1) = \theta$ and $x(2) = \theta'$.

For the function, saved in Pendulum.m

```
\begin{aligned} & \text{function xdot} = \text{Pendulum}(x,t) \\ & c = -1; \\ & \text{xdot}(1) = & \text{x}(2); \\ & \text{xdot}(2) = & \text{c*sin}(x(1)); \\ & \text{endfunction} \end{aligned} And to run it & \text{x0} = [0,2.0]; \\ & \text{t=linspace}(0,50,250)'; \\ & \text{x=lsode}(\text{``Pendulum''},x0,t); \\ & \text{plot}(t,x) \end{aligned}
```