## Problem Set 6

1. (i) Let 
$$F : \mathbb{R}^3 \to \mathbb{R}$$
 be the function  $F\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = e^x \sin(y) + \cos(x + y - 2z)$ . Find the degree 3  
Taylor polynomial of  $F$  at the point  $\mathbf{c} = \begin{bmatrix} 2 \\ \frac{\pi}{6} \\ 1 \end{bmatrix}$ .

**Solution.** The Taylor polynomial of the sum of two functions is equal to the sum of Taylor polynomials. So we can compute the Taylor polynomials  $R_3$  and  $S_3$  of the functions  $G(x,y,z) = e^x \sin(y)$  and  $H(x,y,z) = \cos(x + y - 2z)$  centered at **c** separately and then add them up to find the Taylor polynomial  $T_3$  of F centered at **c**. To start, we firstly compute partial derivatives of G with order at most three. Notice that G depends only on x and y and the partial derivative with respect to z and higher order partial derivatives which contain z are equal to zero. So we focus on partial derivatives with respect to x and y.

	at(x,y,z)	at c			
G	$e^x \sin(y)$	$\frac{1}{2}e^2$		at(x,y,z)	$at \ c$
$\frac{\partial G}{\partial x}$	$e^x \sin(y)$	$\frac{1}{2}e^2$	$rac{\partial^3 G}{\partial x^3}$	$e^x \sin(y)$	$\frac{1}{2}e^2$
$rac{\partial G}{\partial y}$	$e^x \cos(y)$	$\frac{\sqrt{3}}{2}e^2$	$\frac{\partial^3 G}{\partial x^2 \partial y}$	$e^x \cos(y)$	$\frac{\sqrt{3}}{2}e^2$
$\frac{\partial^2 G}{\partial x^2}$	$e^x \sin(y)$	$\frac{1}{2}e^2$	$\frac{\partial^3 G}{\partial x \partial y^2}$	$-e^x\sin(y)$	$-\frac{1}{2}e^2$
$\frac{\partial^2 G}{\partial y^2}$	$-e^x\sin(y)$	$-\frac{1}{2}e^{2}$	$rac{\partial^3 G}{\partial y^3}$	$e^x \cos(y)$	$-\frac{\sqrt{3}}{2}e^2$
$\frac{\partial^2 G}{\partial x \partial y}$	$e^x \cos(y)$	$\frac{\sqrt{3}}{2}e^2$	L	1	1

Using general formula for the Taylor polynomials we can write

$$R_{3}(\mathbf{c} + \begin{bmatrix} h\\k\\l \end{bmatrix}) = \frac{1}{2}e^{2} + \frac{1}{2}e^{2}h + \frac{\sqrt{3}}{2}e^{2}k + \frac{1}{4}e^{2}h^{2} + \frac{\sqrt{3}}{2}e^{2}hk - \frac{1}{4}e^{2}k^{2} + \frac{1}{12}e^{2}h^{3} + \frac{\sqrt{3}}{4}e^{2}h^{2}k - \frac{1}{4}e^{2}hk^{2} - \frac{\sqrt{3}}{12}e^{2}k^{3}.$$

To compute  $S_3$ , we note that the function G is composition of the linear function x + y - 2z. The Taylor polynomial  $S'_3$  of the linear function x + y - 2z at **c** is given by itself and hence we have

$$S'_{3}(\mathbf{c} + \begin{bmatrix} h\\k\\l \end{bmatrix}) = (2+h) + (\frac{\pi}{6}+k) - 2(1+l) = \frac{\pi}{6} + h + k - 2l.$$

The degree three Taylor polynomial  $S''_3$  of  $\cos(x)$  centered at the point  $\frac{\pi}{6} = 2 + \frac{\pi}{6} - 2 \times 1$  is equal to

$$S_3''(\frac{\pi}{6}+t) = \cos(\frac{\pi}{6}) - \sin(\frac{\pi}{6})t - \frac{\cos(\frac{\pi}{6})}{2}t^2 + \frac{\sin(\frac{\pi}{6})}{6}t^3 = \frac{\sqrt{3}}{2} - \frac{1}{2}t - \frac{\sqrt{3}}{4}t^2 + \frac{1}{12}t^3$$

Therefore, the Taylor polynomial of the composed function G is given as

$$S_{3}(\mathbf{c} + \begin{bmatrix} h\\k\\l \end{bmatrix}) = \frac{\sqrt{3}}{2} - \frac{1}{2}(h+k-2l) - \frac{\sqrt{3}}{4}(h+k-2l)^{2} + \frac{1}{12}(h+k-2l)^{3}$$
  
By adding up  $R_{3}(\mathbf{c} + \begin{bmatrix} h\\k\\l \end{bmatrix})$  and  $S_{3}(\mathbf{c} + \begin{bmatrix} h\\k\\l \end{bmatrix})$  we obtain the desired Taylor polynomial  $T_{3}(\mathbf{c} + \begin{bmatrix} h\\k\\l \end{bmatrix})$ .  
$$\begin{bmatrix} h\\k\\l \end{bmatrix}$$
).

(*ii*) Find the degree 3 Taylor polynomial of  $F : \mathbb{R}^3 \to \mathbb{R}$  given by  $F\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = e^{x+2y^2+3z^3}$  centered

at the point 
$$\mathbf{c} = \begin{bmatrix} 0\\ 0\\ 0 \end{bmatrix}$$
.

**Solution.** Since  $G(x,y,z) = x + 2y^2 + 3z^3$  is a polynomial of degree 3, the degree 3 polynomial  $S_3$  of  $x + 2y^2 + 3z^3$  centered at the point **c** is

$$S_3\left(\left[\begin{array}{c}x\\y\\z\end{array}\right]\right) = x + 2y^2 + 3z^3.$$

The degree Taylor polynomial  $R_3$  of  $h(t) = e^t$  at the point  $G(\mathbf{c}) = 0$  is equal to

$$R_3(t) = 1 + t + \frac{t^2}{2} + \frac{t^3}{6}$$

Thus the degree Taylor polynomial  $T_3$  of F at **c** is given by composing  $R_3$  and  $S_3$  and then dropping terms of degree higher than 3.

$$R_3 \circ S_3(\begin{bmatrix} x\\ y\\ z \end{bmatrix}) = R_3(x+2y^2+3z^3) = 1 + (x+2y^2+3z^3) + \frac{(x+2y^2+3z^3)^2}{2} + \frac{(x+2y^2+3z^3)^3}{6} = 0$$

$$1 + (x + 2y^2 + 3z^3) + \frac{(x + 2y^2)^2}{2} + \frac{x^3}{6} + o(\| \begin{bmatrix} x\\ y\\ z \end{bmatrix} \|^3) = 1 + (x + 2y^2 + 3z^3) + \frac{x^2 + 4xy^2}{2} + \frac{x^3}{6} + o(\| \begin{bmatrix} x\\ y\\ z \end{bmatrix} \|^3)$$

Consequently, we have

$$T_{3}\left(\begin{bmatrix} x\\ y\\ z \end{bmatrix}\right) = 1 + x + \frac{x^{2}}{2} + 2y^{2} + \frac{x^{3}}{6} + \frac{4xy^{2}}{2} + 3z^{3}.$$

- 2. Let  $f(x,y) = x^2 y(y-1)^2$ , and let  $V = \{(x,y) : f(x,y) = 0\}$ . In the last problem set, you studied the set V using the implicit function theorem.
  - (i) Show that in a neighborhood of  $(0,0) \in V$ , the set V can be described locally as the graph of a function  $y = \phi(x)$ . (Recall that last week you showed at any point in V, except (0,0) and (0,1), the set V can be described locally as the graph of a function  $x = \psi(y)$ .)

Solution.

 $J_{(x,y)}f = \begin{bmatrix} 2x & -3y^2 + 4y - 1 \end{bmatrix} \implies J_{(0,0)}f = \begin{bmatrix} 0 & -1 \end{bmatrix}$ 

Since the second entry of  $J_{(0,0)}f$ , which is  $\frac{\partial f}{\partial y}(0,0)$  is non-zero, the implicit function theorem implies that the set V in a neighborhood of (0,0) can be described as the graph of a function  $y = \phi(x)$  with  $\phi(0) = 0$ .

(ii) Find  $\phi'(0)$  for the function that you found in the first part.

**Solution.** The implicit function theorem implies that  $\phi'(0) = -LR^{-1}$ , where R and L are given by

$$J_{(0,0)}f = \begin{bmatrix} 0 & -1 \end{bmatrix} = \begin{bmatrix} L & R \end{bmatrix}$$

Therefore,  $\phi'(0) = 0$ .

(iii) Find the degree 3 Taylor polynomial of  $\phi$  centered at 0.

**Solution.** Since  $\phi(0) = 0$  and  $\phi'(0) = 0$ , the the degree 3 Taylor polynomial  $T_3$  of  $\phi$  centered at 0 has the following form

$$T_3(x) = ax^2 + cx^3$$

Using the properties of Taylor polynomials for functions defined implicitly, which we discussed in the class, we know that  $f(x,T_3(x))$  does not have any term of degree lower than 4. That is to say:

$$x^{2} - (ax^{2} + cx^{3})(ax^{2} + cx^{3} - 1)^{2} = o(x^{3}) \implies (1 - a)x^{2} - cx^{3} = o(x^{3})$$

This shows that a = 1 and c = 0.

3. Suppose  $V \subset \mathbb{R}^3$  is the set of points (x,s,t) which satisfy the following equation

$$F(x,s,t) = x^3 + xs + t^2 - 2.$$

Notice that the point (-1,1,2) is an element of V.

(i) Use the implicit function theorem to show that there are neighborhoods B of (1,2) and W of -1and a function  $\varphi: B \to W$  such that  $V \cap (W \times B)$  is given by the graph of the function  $\phi$ :

$$G_{\phi} = \{ (\phi(s,t), s, t) \mid (s,t) \in B \}$$

Solution.

$$J_{(x,s,t)}F = \begin{bmatrix} 3x^2 + s & x & 2t \end{bmatrix} \implies J_{(-1,1,2)}F = \begin{bmatrix} 4 & -1 & 4 \end{bmatrix}$$

Since the first entry of  $J_{(-1,1,2)}F$ , which is  $\frac{\partial f}{\partial x}(-1,1,2)$  is non-zero, the implicit function theorem implies that the set V in a neighborhood of (-1,1,2) can be described as the graph of a function  $x = \phi(s,t)$  with  $\phi(1,2) = -1$ .

(ii) Find the degree 2 Taylor polynomial of  $\varphi$  centered at (1,2).

**Solution.** The implicit function theorem implies that  $J_{(1,2)}\phi = -L^{-1}R$ , where R and L are given by

$$J_{(-1,1,2)}F = \begin{bmatrix} 4 & -1 & 4 \end{bmatrix} = \begin{bmatrix} L & R \end{bmatrix} \implies L = \begin{bmatrix} 4 \end{bmatrix}, R = \begin{bmatrix} -1 & 4 \end{bmatrix}.$$

Therefore,  $J_{(1,2)}\phi = \begin{bmatrix} 1 & -1 \end{bmatrix}$ .

The computation of  $\phi(1,2)$  and  $J_{(1,2)}\phi$  shows that the degree 2 Taylor polynomial  $T_2$  of  $\varphi$  centered at (1,2) has the following form.

$$T_2(1+h,2+k) = -1 + \frac{1}{4}h - k + ah^2 + bhk + ck^2.$$

In order to determine a, b and c, we use the fact that if we plug in  $T_2(1+h,2+k)$  for x, 1+h for s and 2+k for t in  $F(x,s,t) = x^3 + xs + t^2 - 2$ , there does not exists in any term in terms of h and k with degree less than 2

$$F(T_2(1+h,2+k),1+h,2+k) =$$

$$=(-1+\frac{1}{4}h-k+ah^{2}+bhk+ck^{2})^{3}+(-1+\frac{1}{4}h-k+ah^{2}+bhk+ck^{2})(1+h)+(2+k)^{2}-2hk^{2}+bhk^$$

After dropping terms with degree higher than 2, we obtain

$$-3(\frac{1}{4}h-k)^2 + 4(ah^2 + bhk + ck^2) + h(\frac{1}{4}h-k) + k^2 = 0 \implies (\frac{1}{16} + 4a)h^2 + (\frac{1}{2} + 4b)hk + (-2 + 4c)k^2 = 0$$

The last identity shows that  $a = -\frac{1}{64}$ ,  $b = -\frac{1}{8}$  and  $c = \frac{1}{2}$ .

4. Suppose  $F : \mathbb{R}^3 \to \mathbb{R}^2$  is a  $C^1$  function and  $V = \{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : F\left( \begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = 0 \}$ , and for  $\mathbf{c} \in V$ 

$$J_{\vec{c}}(F) = \left[ \begin{array}{rrr} 4 & 5 & -6 \\ -6 & 8 & 9 \end{array} \right].$$

(i) Which variables (out of x, y, and z) can be chosen as the free variable so that the implicit function theorem implies that at  $\vec{c}$ , V is locally the graph of a function of the free variable? Explain briefly.

Solution. The  $2 \times 2$  matrices

$$\left[\begin{array}{cc}4&5\\-6&8\end{array}\right],\qquad \left[\begin{array}{cc}5&-6\\8&9\end{array}\right]$$

obtained by removing the last column (corresponding to the variable z) and the first column (corresponding to the variable x) from  $J_{\vec{c}}(F)$  are invertible because

$$\det \begin{bmatrix} 4 & 5\\ -6 & 8 \end{bmatrix} = 62 \neq 0, \qquad \begin{bmatrix} 5 & -6\\ 8 & 9 \end{bmatrix} = 93 \neq 0.$$

Therefore, by the implicit function theorem, we may use x and z as the free variables so that V in a neighborhood of c can be described as the graph of a function of the variable x or z. However, we cannot use the implicit function theorem for the variable y because the matrix obtained from  $J_{\vec{c}}(F)$  by removing the second column (corresponding to the variable y) is

$$\left[\begin{array}{rr} 4 & -6 \\ -6 & 9 \end{array}\right]$$

which has vanishing determinant and hence it is not invertible.

(ii) Give an example of a  $2 \times 3$  matrix A such that if  $J_{\vec{c}}(F) = A$  in the setup above, then exactly one of the variables can be free, but not either of the other two. Explain briefly.

Solution. Let

The  $2 \times 2$  matrix

A =	$\left[ \begin{array}{c} 1\\ 1 \end{array} \right]$	$\frac{2}{3}$	0 0
[	1 1	$\begin{bmatrix} 2\\ 3 \end{bmatrix}$	

obtained from removing the last column of A is invertible because its determinant is equal to 1. Thus we may use the variable z to represent V in a neighborhood of c as the graph of a function of z. However, we may not use the other two variables because the matrices obtained from removing the first or the second column are not invertible:

$\begin{bmatrix} 2 \end{bmatrix}$	0		1	0	]
3	0	,	1	0	] .

5. Suppose  $P : \mathbb{R}^3 \to \mathbb{R}$  is the polynomial  $p(\vec{h}) = \vec{h}^{\alpha}$  for  $\alpha \in \mathbb{N}^3$ . To be more specific, if  $\vec{h} = \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix}$  and  $\vec{h} = \begin{bmatrix} h_1 \\ h_2 \\ h_3 \end{bmatrix}$ 

 $\alpha = (\alpha_1, \alpha_2, \alpha_3), \text{ then } p(\vec{h}) = h_1^{\alpha_1} h_2^{\alpha_2} h_3^{\alpha_3}. \text{ Find partial derivatives of arbitrary oder of the function } p \text{ at the point } \vec{h} = \begin{bmatrix} 0\\0\\0 \end{bmatrix}.$ 

Solution. We have

$$\frac{\partial^{i+j+k}p}{\partial^i h_1 \partial^j h_2 \partial^k h_3}(\vec{h}) = \alpha_1(\alpha_1 - 1) \dots (\alpha_1 - i + 1)\alpha_2(\alpha_2 - 1) \dots (\alpha_2 - j + 1)\alpha_3(\alpha_3 - 1) \dots (\alpha_3 - k + 1)h_1^{\alpha_1 - i}h_2^{\alpha_2 - j}h_3^{\alpha_3 - k}.$$

From this it can be easily seen that

$$\frac{\partial^{i+j+k}p}{\partial^i h_1 \partial^j h_2 \partial^k h_3} \begin{pmatrix} 0\\0\\0 \end{pmatrix} = \begin{cases} \alpha_1! \alpha_2! \alpha_3! & i = \alpha_1, j = \alpha_2, k = \alpha_k \\ 0 & \text{otherwise} \end{cases}$$

6. Suppose  $F : \mathbb{R}^2 \to \mathbb{R}$  and  $g : \mathbb{R} \to \mathbb{R}$  are  $C^{\infty}$  functions. Suppose  $F(\begin{bmatrix} 0\\0 \end{bmatrix}) = 0$ . Suppose the degree 2 Taylor polynomial of F at the point  $\begin{bmatrix} 0\\0 \end{bmatrix}$  is

$$T_2\left(\left[\begin{array}{c}h\\k\end{array}\right]\right) = a_1h + a_2k + b_1h^2 + b_2hk + b_3k^2$$

and the degree 2 Taylor polynomial of g at 0 is

$$S_2(l) = c + dl + el^2$$

(i) Determine the constants  $a_i$ ,  $b_j$ , c, d and e in terms of partial derivatives of F at  $\begin{bmatrix} 0\\0 \end{bmatrix}$  and the derivatives of g at 0.

Solution. The formulas for Taylor polynomials imply that

$$a_1 = \frac{\partial F}{\partial x}(0,0), \quad a_2 = \frac{\partial F}{\partial y}(0,0), \quad b_1 = \frac{1}{2}\frac{\partial^2 F}{\partial x^2}(0,0), \quad b_2 = \frac{\partial^2 F}{\partial x \partial x}(0,0), \quad b_3 = \frac{1}{2}\frac{\partial^2 F}{\partial y^2}(0,0),$$
  
and

$$c = g(0),$$
  $d = g'(0),$   $e = \frac{1}{2}g''(0).$ 

(ii) Suppose R is the polynomial of degree 2 obtained by forming the composition  $S_2 \circ T_2$  and then erasing the terms of degree greater than 2. Use your answer to the first part to determine R in terms of the partial derivatives of F at  $\begin{bmatrix} 0\\0 \end{bmatrix}$  and the derivatives of g at 0.

Solution.

$$S_{2} \circ T_{2}(\begin{bmatrix} h \\ k \end{bmatrix}) = c + d(a_{1}h + a_{2}k + b_{1}h^{2} + b_{2}hk + b_{3}k^{2}) + e(a_{1}h + a_{2}k + b_{1}h^{2} + b_{2}hk + b_{3}k^{2})^{2}$$

$$\implies R_{2}(\begin{bmatrix} h \\ k \end{bmatrix}) = c + (da_{1})h + (da_{2})k + (db_{1} + ea_{1}^{2})h^{2} + (db_{2} + 2ea_{1}a_{2})hk + (db_{3} + ea_{2}^{2})k^{2} =$$

$$= g(0) + (g'(0)\frac{\partial F}{\partial x}(0,0))h + (g'(0)\frac{\partial F}{\partial y}(0,0))k + (g'(0)\frac{1}{2}\frac{\partial^{2} F}{\partial x^{2}}(0,0) + e\frac{\partial F}{\partial x}(0,0)^{2})h^{2} +$$

$$+ (g'(0)\frac{\partial^{2} F}{\partial x \partial y}(0,0) + 2e\frac{\partial F}{\partial x}(0,0)\frac{\partial F}{\partial y}(0,0))hk + (\frac{1}{2}g'(0)\frac{\partial^{2} F}{\partial y^{2}}(0,0) + e\frac{\partial F}{\partial y}(0,0)^{2})k^{2}$$

(iii) Show that R is equal to the degree 2 Taylor polynomial of the composed function  $g \circ F : \mathbb{R}^2 \to \mathbb{R}$ . (Hint: To show this you have to relate the coefficients of R to the partial derivatives of  $g \circ F$  at  $\begin{bmatrix} 0\\0 \end{bmatrix}$ . Use chain rule (for one variable functions) to establish this relation.)

Notice that this is a special case of a general result about Taylor polynomials of composed functions that we stated in the class. The proof of the general case is similar.

Solution. Clearly we have

$$g \circ F\left(\begin{bmatrix} 0\\0 \end{bmatrix}\right) = g(0). \tag{1}$$

This shows that the constant term in  $R_2$  matches with the constant term in the degree 2 Taylor polynomial of  $g \circ F$  centered at  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ .

Using chain rule we may write:

$$\frac{\partial(g \circ F)}{\partial x}(x,y) = g'(F(x,y))\frac{\partial F}{\partial x}(x,y), \qquad \frac{\partial(g \circ F)}{\partial y}(x,y) = g'(F(x,y))\frac{\partial F}{\partial y}(x,y).$$

By plugging in (0,0) for (x,y) in the above identities we can see that the coefficient of h and k in  $R_2$  and the degree 2 Taylor polynomial of  $g \circ F$  centered at  $\begin{bmatrix} 0\\0 \end{bmatrix}$  match.

By differentiating the two identities in (1) and applying the product rule and the chain rule we obtain

$$\frac{\partial^2 (g \circ F)}{\partial x^2}(x,y) = g'(F(x,y))\frac{\partial^2 F}{\partial x^2}(x,y) + g''(F(x,y))(\frac{\partial F}{\partial x}(x,y))^2,$$
$$\frac{\partial^2 (g \circ F)}{\partial x \partial y}(x,y) = g'(F(x,y))\frac{\partial^2 F}{\partial x \partial y}(x,y) + g''(F(x,y))\frac{\partial F}{\partial x}(x,y)\frac{\partial F}{\partial y}(x,y)$$

and

$$\frac{\partial^2 (g \circ F)}{\partial y^2}(x,y) = g'(F(x,y))\frac{\partial^2 F}{\partial y^2}(x,y) + g''(F(x,y))(\frac{\partial F}{\partial y}(x,y))^2$$

By plugging in (0,0) for (x,y) in the above identities we can see that the coefficient of  $h^2$ , hk and  $k^2$  in  $R_2$  and the degree 2 Taylor polynomial of  $g \circ F$  centered at  $\begin{bmatrix} 0\\0 \end{bmatrix}$  match.