

## Lecture 2: Row reduction

Using the "Replace", "Swap", and "Scale" row-operations, we shall now discuss how to put any matrix in a particularly nice form:

### Reduced Row-Echelon Form (RREF)

A matrix  $A$  is in RREF if all of the following hold:

(i) the first nonzero entry of each row is 1, called a "leading 1";

(ii) when a column contains a leading 1, all other entries in that column are 0 (this is called a "pivot column"); and

(iii) when a row contains a leading 1, each row above it contains a leading 1 to the left.

The weaker notion of Row-Echelon Form (REF) is obtained by dropping (i) and weakening (ii) and (iii):

(ii') when a column contains the first nonzero entry of some row, all the entries of the column

below it are 0 ; and

(iii') the leading nonzero entry of a row occurs further to the right than all the leading entries in the rows above it.

Ex 1 / If "\*" stands for "arbitrary numbers",  
then

$$\begin{pmatrix} 1 & * & 0 & * & * \\ 0 & 0 & 1 & * & * \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \text{ and } \begin{pmatrix} 1 & 0 & * & * & 0 \\ 0 & 1 & * & * & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} \text{ are in}$$

reduced row-echelon form (RREF),

while (if "." stands for "arbitrary NONZERO number")

$$\begin{pmatrix} \bullet & * & * & * & * \\ 0 & 0 & \bullet & * & * \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \text{ and } \begin{pmatrix} \bullet & * & \bullet & * & * \\ 0 & \bullet & * & * & * \\ 0 & 0 & 0 & 0 & \bullet \end{pmatrix} \text{ are in}$$

row-echelon form (REF).

Row reduction means "some procedure for associating an RREF matrix to a given matrix  $A$ ":

$$A \mapsto \text{rref}(A).$$

Since the procedure simply applies row operations to  $A$ , the new matrix is row-equivalent to  $A$ .

FACT: There is exactly one RREF matrix row-equivalent to a given matrix  $A$ .

(We'll explain why in Lecture 3.)

CONSEQUENCE:  $\text{rref}(A)$  is independent of the procedure used!

Here is one such procedure — I'd suggest using it when you don't immediately see a shortcut.

## Row-reduction algorithm

- (a) "cursor" starts at upper left-hand entry of matrix;
- (b) move cursor to right if the cursor entry and all entries below it are 0; repeat until this is no longer the case;
- (c) if cursor entry = 0, swap cursor row with the first row below it having nonzero entry in the cursor column; ] SWAP
- (d) divide cursor row by cursor entry; ] SCALE
- (e) eliminate all other entries in the cursor column by adding suitable multiples of the cursor row to other rows; } REPLACE
- (f) if cursor is at bottom right, STOP.  
Otherwise, move down & to the right, and go back to (b).

Let's illustrate with an example:  $\square$  = cursor

Ex 2 /  $A = \begin{pmatrix} \square 0 & 1 & -1 & -1 \\ 2 & 4 & 2 & 4 & 2 \\ 2 & 4 & 3 & 3 & 3 \\ 3 & 6 & 6 & 3 & 6 \end{pmatrix} \xrightarrow{(c)} \begin{pmatrix} \square 4 & 2 & 4 & 2 \\ 0 & 0 & 1 & -1 & -1 \\ 2 & 4 & 3 & 3 & 3 \\ 3 & 6 & 6 & 3 & 6 \end{pmatrix} \xrightarrow{(d)} \begin{pmatrix} \square 1 & 2 & 1 & 2 & 1 \\ 0 & 0 & 1 & -1 & -1 \\ 2 & 4 & 3 & 3 & 3 \\ 3 & 6 & 6 & 3 & 6 \end{pmatrix}$

$\begin{pmatrix} \square 1 & 2 & 1 & 2 & 1 \\ 0 & \square 1 & -1 & -1 \\ 0 & \square 0 & 1 & -1 & 1 \\ 0 & 0 & 3 & -3 & 3 \end{pmatrix} \xrightarrow{(e)} \begin{pmatrix} 1 & 2 & 0 & 3 & 2 \\ 0 & 0 & \square 1 & -1 & -1 \\ 0 & 0 & 0 & \square 0 & \square 2 \\ 0 & 0 & 0 & 0 & 6 \end{pmatrix} \xrightarrow{(d)} \begin{pmatrix} 1 & 2 & 0 & 3 & 2 \\ 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 & \square 1 \\ 0 & 0 & 0 & 0 & 6 \end{pmatrix}$

$\begin{pmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & \square 1 \\ 0 & 0 & 0 & 0 & \square 0 \end{pmatrix} = \text{rref}(A).$

Now, how do we use this to solve a linear system?

STEP 1: Convert the system to an augmented matrix

$$M = [A \mid \vec{b}]$$

STEP 2: Apply the above algorithm to compute  $\text{rref}(M)$ .

STEP 3: Convert back to a linear system and find the tuples  $(x_1, \dots, x_n)$  solving it. (More precisely: use the non-pivot variables to parameterize the solution set. This is sometimes called "back substitution".)

Ex 3/

$$\begin{cases} 3x_1 - 6x_2 + 2x_3 - x_4 = 1 \\ -2x_1 + 4x_2 + x_3 + 3x_4 = 4 \\ x_3 + x_4 = 2 \\ x_1 - 2x_2 + x_3 = 1 \end{cases}$$

STEP 1

$$M = \left[ \begin{array}{cccc|c} 3 & -6 & 2 & -1 & 1 \\ -2 & 4 & 1 & 3 & 4 \\ 0 & 0 & 1 & 1 & 2 \\ 1 & -2 & 1 & 0 & 1 \end{array} \right] \xrightarrow[\substack{\text{scale} \\ P_1 \rightarrow \frac{1}{3}P_1}]{\quad} \left[ \begin{array}{cccc|c} 1 & -2 & \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \\ -2 & 4 & 1 & 3 & 4 \\ 0 & 0 & 1 & 1 & 2 \\ 1 & -2 & 1 & 0 & 1 \end{array} \right]$$

$$\left[ \begin{array}{cccc|c} 1 & -2 & \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \\ 0 & 0 & \frac{7}{3} & \frac{7}{3} & \frac{11}{3} \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & \frac{1}{3} & \frac{1}{3} & \frac{2}{3} \end{array} \right] \xrightarrow[\substack{\text{scale} \\ P_2 \rightarrow \frac{3}{7}P_2}]{\substack{\text{replace} \\ \begin{cases} P_2 \rightarrow P_2 + 2P_1 \\ P_4 \rightarrow P_4 - P_1 \end{cases}}} \left[ \begin{array}{cccc|c} 1 & -2 & \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & \frac{1}{3} & \frac{1}{3} & \frac{2}{3} \end{array} \right] \quad \text{STEP 2}$$

$$\left[ \begin{array}{cccc|c} 1 & -2 & 0 & -1 & -1 \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow[\substack{\text{replace} \\ \begin{cases} P_3 \rightarrow P_3 - P_2 \\ P_4 \rightarrow P_4 - \frac{1}{3}P_2 \\ P_1 \rightarrow P_1 - \frac{2}{3}P_2 \end{cases}}]{\quad} = \text{ref}(M)$$

STEP 3

$$\left. \begin{array}{l} x_1 - 2x_2 - x_4 = -1 \\ x_3 + x_4 = 2 \end{array} \right\}$$

Solve for the variables corresponding to pivot columns, called basic variables:

$$\begin{cases} x_1 = 2x_2 + x_4 - 1 \\ x_3 = 2 - x_4 \end{cases}$$

The free variables are the non-pivot ones, and are so named because they can be freely chosen. They parametrize the solution set of the linear system:

$$\mathcal{S} = \left\{ (2x_2 + x_4 - 1, x_2, 2 - x_4, x_4) \mid x_2, x_4 \in \mathbb{R} \right\} //$$

Ex 4 /

$$\begin{cases} 3x_1 - 6x_2 + 2x_3 - x_4 = 1 \\ -2x_1 + 4x_2 + x_3 + 3x_4 = 4 \\ x_3 + x_4 = 2 \\ x_1 - 2x_2 + x_3 = 0 \end{cases} \quad \leftarrow \text{same as Ex. 3 except for this}$$

$$\left[ \begin{array}{cccc|c} 3 & -6 & 2 & -1 & 1 \\ -2 & 4 & 1 & 3 & 4 \\ 0 & 0 & 1 & 1 & 2 \\ 1 & -2 & 1 & 0 & 0 \end{array} \right] \xrightarrow[\text{Ex. 3}]{\text{steps from}} \left[ \begin{array}{cccc|c} 1 & -2 & 0 & -1 & -1 \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 \end{array} \right]$$

swap  $p_3 \leftrightarrow p_4$

$$\left[ \begin{array}{cccc|c} 1 & -2 & 0 & -1 & -1 \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow[\substack{\text{scale} \\ p_3 \rightarrow -1 \cdot p_3}]{\text{scale}} \left[ \begin{array}{cccc|c} 1 & -2 & 0 & -1 & -1 \\ 0 & 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\left[ \begin{array}{cccc|c} 1 & -2 & 0 & -1 & 0 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow[\substack{\text{replace} \\ p_1 \rightarrow p_1 + p_3 \\ p_2 \rightarrow p_2 - 2p_3}]{\text{replace}} \left\{ \begin{array}{l} x_1 - 2x_2 - x_4 = 0 \\ x_3 + x_4 = 0 \\ \boxed{0 = 1} \end{array} \right.$$

Solution set

$$\mathcal{S} = \emptyset$$

System is inconsistent! //

From the last example, we notice that

- If the last column of the augmented matrix is a pivot column, then the system is inconsistent.

Otherwise, steps 1-3 tell us how to solve the system, and so:

- If the last column is non-pivot, the system is consistent; it has a unique solution if there are no free variables, i.e. if all but the last column are pivots.

So far we have looked at  $m$  equations in  $n$  unknowns, with  $m = n$ . What about the other cases?

- If  $m > n$ , the system is called overdetermined.
- If  $m < n$ , the system is called underdetermined.

Q: Can an overdetermined system be consistent?

A: YES. But some equations will have to be "linear combinations" of others.

Q: Can an underdetermined system have a unique solution?

A: NO. Think about intersections of planes in space: two planes in 3-space will never intersect in a point.

A more mathematical answer can be formulated as follows:

When you reduce an augmented matrix of the form

$$\begin{matrix} m \\ \updownarrow \\ \left[ \begin{array}{c} \phantom{0} \\ \phantom{0} \\ \phantom{0} \end{array} \right] \end{matrix} \quad \begin{matrix} \leftarrow n \rightarrow \\ \phantom{0} \\ \phantom{0} \\ \phantom{0} \end{matrix} \quad (m < n)$$

to RREF, there must be non-pivot columns, hence free variables. This is because each pivot column contains a leading 1 for some row, and there are only  $m$  rows hence  $\leq n$  leading 1's. In general, the number of pivots is at most the smaller of  $m$  &  $n$ .