

Lecture 44 : Surface area

For most of the remainder of this course we shall work in \mathbb{R}^3 .

We know how to integrate on

- curves in \mathbb{R}^3 &
- solid regions in \mathbb{R}^3 ;

What's left is

- surfaces in \mathbb{R}^3 .

Here are 3 ways to describe a surface:

→ implicitly: as level surface $F(x,y,z) = 0$

→ explicitly: as graph $z = f(x,y)$ (or $y = f(x,z)$, etc.)

→ parametrically: $(u,v) \mapsto (X(u,v), Y(u,v), Z(u,v)) =: \vec{r}(u,v)$
where $(u,v) \in \mathcal{T} \subset \mathbb{R}^2$.

Ex 1/ Cylinder of radius R & height h :

$$\begin{aligned} \text{implicit: } x^2 + y^2 = R^2 \\ \text{explicit: } y = \pm \sqrt{R^2 - x^2} \end{aligned} \quad \left. \begin{aligned} & \text{and} \\ & 0 \leq z \leq h \end{aligned} \right\}$$

$$\begin{aligned} \text{parametric: } \vec{r}(u,v) = (R \cos u, R \sin u, v) \\ (u,v) \in [0, 2\pi] \times [0, h] \end{aligned}$$

//

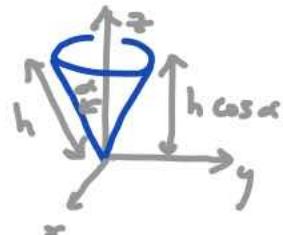
Ex 2/ Sphere of radius R :

$$\begin{aligned} \text{implicit: } x^2 + y^2 + z^2 = R^2 \\ \text{explicit: } z = \pm \sqrt{R^2 - x^2 - y^2} \end{aligned}$$

$$\begin{aligned} \text{parametric: } \vec{r}(u,v) = (R \cos u \sin v, R \sin u \sin v, R \cos v) \\ (u,v) \in [0, 2\pi] \times [0, \pi] \end{aligned}$$

//

Ex 3/ Cone of vertical angle α and "height" h :



Implicit: $x^2 + y^2 = z^2 \tan(\alpha)$ ($\frac{z}{r} = \tan \alpha$) parametric:

Explicit: $z = \cot(\alpha) \sqrt{x^2 + y^2}$

$\vec{r}(u, v) = (v \sin u \cos v, v \sin u \sin v, v \cos u)$ //

To be more explicit about what sorts of surfaces we'll work with:

Let

- $\tilde{T} \subset \mathbb{R}^2$ (coords. u, v) be a region w/piecewise smooth boundary $\partial \tilde{T}$
- $\vec{r}: \tilde{T} \rightarrow \mathbb{R}^3$ be a 1-to-1, C^1 map (technically, we want this to extend to an open set containing \tilde{T})
- $\mathcal{S} := \vec{r}(\tilde{T})$ the image of \vec{r} .

Definition: \vec{r} is a smooth parametrization of \mathcal{S} if $\vec{r}_u \times \vec{r}_v$ is never zero. \mathcal{S} is a smooth surface if it has a smooth parametrization (or a union of "open subsets" with such parametrizations).

[For instance, one can show that $\mathcal{S} = \{(x, y, z) \mid F(x, y, z) = 0\}$ is smooth if, at every point on it, F has a nonvanishing partial derivative ("Implicit Function Theorem").]

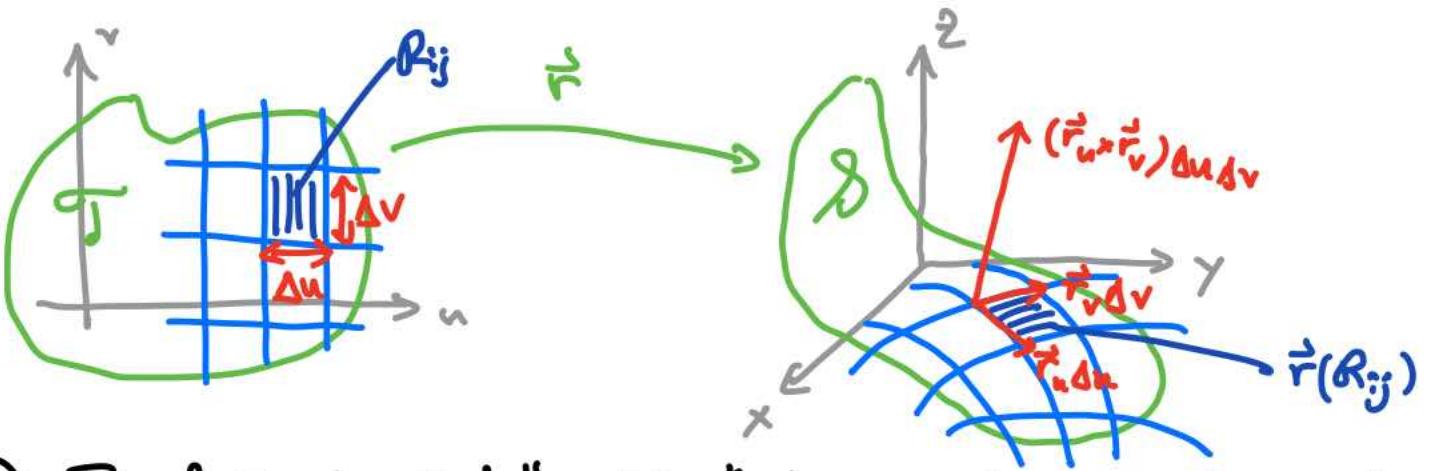
Notes: Write $\vec{r}(u, v) = (X(u, v), Y(u, v), Z(u, v))$

① The condition in the Definition is the same as asking

$$J_{\vec{r}} = \begin{pmatrix} X_u & X_v \\ Y_u & Y_v \\ Z_u & Z_v \end{pmatrix} \quad \text{to have rank 2 everywhere. (Why?)} \\ \vec{r}_u = \begin{pmatrix} X_u \\ Y_u \\ Z_u \end{pmatrix}, \quad \vec{r}_v = \begin{pmatrix} X_v \\ Y_v \\ Z_v \end{pmatrix}$$

② $\vec{r}_u \times \vec{r}_v$ should be viewed as a vector normal to \mathcal{S} ,

with length equal to the ratio of areas $a(\vec{r}(Q_{ij})) / a(Q_{ij})$:



③ If S is described "explicitly" by $z = f(x, y)$, $(x, y) \in D \subset \mathbb{R}^2$,
then it is described parametrically by $\vec{r}(x, y) = (x, y, f(x, y))$.
[So $(u, v) = (x, y)$, $T = D$]

Ex 4 / For the sphere, with $\vec{r}(u, v) = (R\cos u \sin v, R\sin u \sin v, R\cos v)$,

$$\text{we have } \vec{r}_u = (-R\sin u \sin v, R\cos u \sin v, 0),$$

$$\vec{r}_v = (R\cos u \sin v, R\sin u \cos v, -R\sin v)$$

$$\Rightarrow \vec{r}_u \times \vec{r}_v = (-R^2 \cos u \sin^2 v, -R^2 \sin u \sin^2 v, -R^2 \sin v \cos v)$$

$$\|\vec{r}(u, v)\| = R \quad \text{on sphere!} \quad = -R \sin(v) \vec{r}(u, v).$$

$$\Rightarrow \|\vec{r}_u \times \vec{r}_v\| = R^2 \sin(v).$$

Note that this is singular at $v=0$ and π (the north & south poles), and not 1-to-1 at $u=0$ & 2π . But because this happens on a set of content zero in $T = [0, 2\pi] \times [0, \pi]$, it isn't a problem for using the parametrization \vec{r} to integrate over S . //

A bit more on ② & ③ :

- One way to think about $\vec{r}_u(u_0, v_0) \times \vec{r}_v(u_0, v_0)$ being \perp to S at $\vec{r}(u_0, v_0)$ is by showing it is \perp to the tangent vector of any curve $C \subset S$ passing through this point :

view $C = \vec{r}(C^*)$ for $C^* \subset \mathbb{T}$ parametrized by $\vec{\alpha}(t)$,
 so that $\vec{r} \circ \vec{\alpha}$ parametrizes C . Then $\vec{\alpha}'(t) = \begin{pmatrix} u'(t) \\ v'(t) \end{pmatrix}$
 and $(\vec{r} \circ \vec{\alpha})'(t) = \begin{pmatrix} \vec{r}_u & \vec{r}_v \\ \downarrow & \downarrow \\ \vec{r}_u & \vec{r}_v \end{pmatrix} \begin{pmatrix} u'(t) \\ v'(t) \end{pmatrix} = u'(t)\vec{r}_u + v'(t)\vec{r}_v$ is \perp to
 $\vec{r}_u \times \vec{r}_v$.

- In ③, $\vec{r}_u = \vec{r}_x = (1, 0, f_x) \quad \& \quad \vec{r}_v = \vec{r}_y = (0, 1, f_y)$
 $\Rightarrow \vec{r}_u \times \vec{r}_v = (-f_x, -f_y, 1)$.
- If $f(x, y)$ is defined "implicitly" by $F(x, y, f(x, y)) = 0$,
 then recall that applying $\frac{\partial}{\partial x} \Rightarrow F_x + f_x F_z = 0$
 $\Rightarrow f_x = -F_x/F_z$ etc. $\rightarrow \vec{r}_u \times \vec{r}_v = \left(\frac{F_x}{F_z}, \frac{F_y}{F_z}, 1 \right) = \frac{1}{|F_z|} \vec{\nabla} F$.

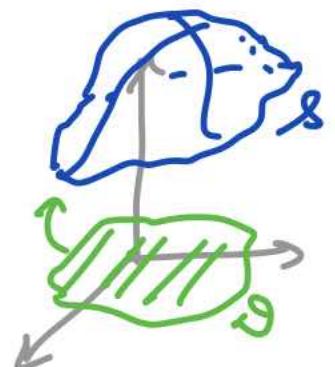


Since $\|\vec{r}_u \times \vec{r}_v\| \Delta u \Delta v$ was the area of the parallelogram approximating $\vec{r}(R_{ij})$, it makes sense to define the surface area of \mathcal{S} by

$$\underline{a}(\mathcal{S}) := \iint_{\mathcal{T}} \|\vec{r}_u \times \vec{r}_v\| du dv$$

in the parametric setting.

- explicit setting: $\iint_D \sqrt{1 + f_x^2 + f_y^2} dx dy$
- implicit setting: $\iint_D \frac{\sqrt{F_x^2 + F_y^2 + F_z^2}}{|F_z|} dx dy$



Ex 5/ Find the surface area of the upper hemisphere of radius R .

- parametric approach: $\iint_{\mathcal{T}} R^2 \sin v du dv = R^2 \int_0^{2\pi} \int_0^{\pi/2} \sin v dv du = 2\pi R^2$
 $(0, 2\pi) \times (0, \pi/2)$

• implicit approach: $\Omega = \text{disk of radius } R$
 $F(x,y,z) = x^2 + y^2 + z^2 - R^2$

$$\iint_{\Omega} \frac{\sqrt{(2x)^2 + (2y)^2 + (2z)^2}}{2z} dx dy = \iint_{\Omega} \frac{2R}{z} dx dy$$

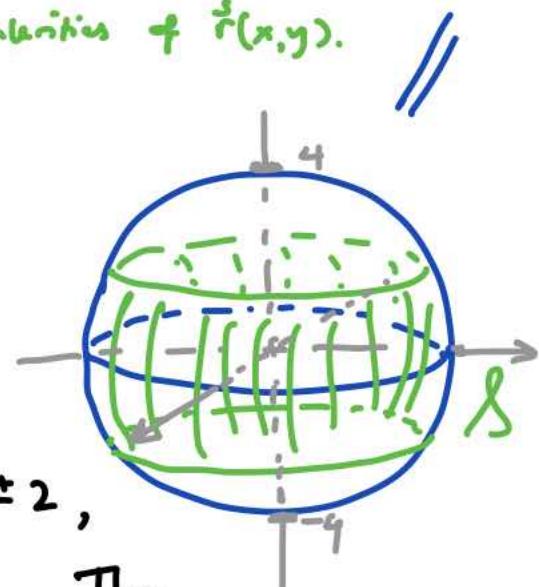
convert to polar
 $c = \sqrt{R^2 - x^2 - y^2} = \sqrt{R^2 - r^2}$

$$= R \int_0^{2\pi} \int_0^R \frac{1}{\sqrt{R^2 - r^2}} r dr d\theta = 2\pi R \int_0^R (R^2 - r^2)^{-1/2} r dr$$

$$= 2\pi R \left[-(R^2 - r^2)^{1/2} \right]_0^R = 2\pi R^2.$$

Technically, one should work with the part of Ω over a disk of radius $R_0 < R$ and take $\lim_{R_0 \rightarrow R}$, to avoid singularities of $\vec{r}(x,y)$.

Ex 6 / Compute the surface area of the part of the sphere of radius $R=4$ between $-2 \leq z \leq 2$.



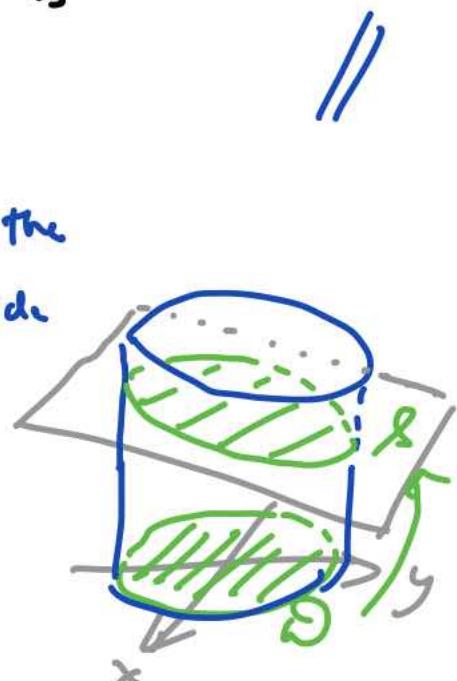
We must limit $4 \cos v (=z)$ to between ± 2 , i.e. $\cos v \in [-\frac{1}{2}, \frac{1}{2}] \Rightarrow v \in [\frac{\pi}{3}, \frac{2\pi}{3}]$. Then

$$a(\Omega) = \int_{\pi/3}^{2\pi/3} \int_0^{2\pi} R^2 \sin v \, dv \, d\theta = 2\pi R^2 \int_{\pi/3}^{2\pi/3} \sin v \, dv$$

$$= 32\pi \left[-\cos v \right]_{\pi/3}^{2\pi/3} = 32\pi.$$

Ex 7 / Find the area of the part of the plane $x+2y+3z=1$ that lies inside the cylinder $x^2+y^2=3$.

Use $z = f(x,y) = \frac{1}{3} - \frac{1}{3}x - \frac{2}{3}y$



$$a(\delta) = \iint_D \sqrt{1 + (-\frac{1}{3})^2 + (-\frac{2}{3})^2} \, dx \, dy = \frac{\sqrt{14}}{3} a(\Omega)$$

$$= \frac{\sqrt{14}}{3} \pi (\sqrt{3})^2 = \pi \sqrt{14}.$$

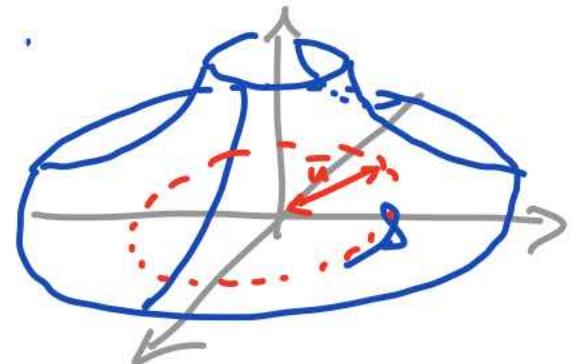
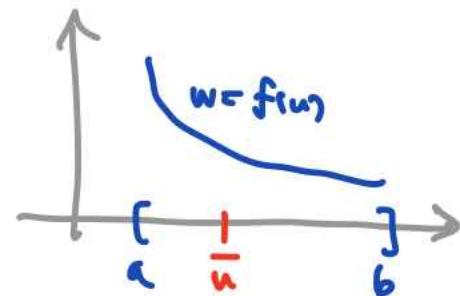
//

Ex 8 / The length of the curve shown
is $l = \int_a^b \sqrt{1+f'(u)^2} \, du$

Its centroid has u -coordinate

$$\bar{u} = \frac{\int_a^b u \sqrt{1+f'(u)^2} \, du}{l}.$$

Find the area of the surface of revolution shown.



Parametrize δ by

$$\vec{r}(u, v) = (u \cos v, u \sin v, f(u)), \quad (u, v) \in [a, b] \times [0, 2\pi]$$

$$\Rightarrow \vec{r}_u = (\cos v, \sin v, f'(u)), \quad \vec{r}_v = (-u \sin v, u \cos v, 0)$$

$$\Rightarrow \vec{r}_u \times \vec{r}_v = u(-f'(u) \cos v, -f'(u) \sin v, 1)$$

$$\Rightarrow \|\vec{r}_u \times \vec{r}_v\| = u \sqrt{1 + (f'(u))^2}$$

$$\Rightarrow a(\delta) = \int_0^{2\pi} \int_a^b u \sqrt{1 + f'(u)^2} \, du \, dv$$

$= 2\pi \bar{u} l$.
 arc length
 of curve
 circumference traced out
 by centroid

//