

## Lecture 24 : Diagonalizing Matrices

Recall that when  $\vec{v} \in \mathbb{R}^n$  is nonzero,  $\lambda \in \mathbb{R}$ , and

$$A\vec{v} = \lambda \cdot \vec{v}, \quad (A = n \times n \text{ matrix})$$

- $\lambda$  (resp.  $\vec{v}$ ) is an eigenvalue (resp. eigenvector) of  $A$ .
- to find eigenvalues : solve  $\det(A - \lambda I_n) = 0$
- to find eigenvectors : for each eigenvalue  $\lambda_0$ , find (a basis for)  
 $E_{\lambda_0} = \text{Nul}(A - \lambda_0 I_n)$   
by row-reduction. Its dimension is  $n - \text{rk}(A - \lambda_0 I_n)$ , by R+N.
- to check if  $\vec{v}_0$  is an eigenvector : Apply  $A$  to  $\vec{v}$
- to check if  $\lambda_0$  is an eigenvalue : see if  $\text{rk}(A - \lambda_0 I_n) < n$   
by using row-reduction.
- the eigenvalues of an upper or lower-triangular matrix are the diagonal entries.



Now by the Fundamental Theorem of Algebra, the characteristic polynomial factors

$$(*) \quad \det(A - \lambda I_n) = (-1)^n (\lambda - \lambda_1) \cdots (\lambda - \lambda_n)$$

where in general the  $\{\lambda_i\}$  may be non-real (i.e. complex numbers) and may not be distinct. Assume for now that they are real.

Definition: The multiplicity of an eigenvalue of  $A$  is the number of times it appears in (\*). (If all multiplicities are 1, then  $A$  has  $n$  distinct eigenvalues.)

Lemma: If  $\vec{v}_1, \dots, \vec{v}_k$  are  $k$  eigenvectors of  $A$  with distinct eigenvalues  $\lambda_1, \dots, \lambda_k$ , then they are linearly independent.

Proof: Use induction: this is clear for  $k=1$ , since  $\vec{v} \neq \vec{0}$  by definition. Assume it holds for  $k-1$  eigenvectors with distinct eigenvalues, i.e. that  $\vec{v}_1, \dots, \vec{v}_{k-1}$  are independent, and let  $\vec{v}_k$  be an eigenvector with a "new" eigenvalue.

Suppose  $\vec{0} = c_1 \vec{v}_1 + \dots + c_k \vec{v}_k$ . (We must show the  $c_i$ 's are all 0.) On one hand (multiplying by  $\lambda_k$ )

$$(1) \quad \vec{0} = c_1 \lambda_k \vec{v}_1 + \dots + c_k \lambda_k \vec{v}_k.$$

On the other hand (applying  $A$ )

$$(2) \quad \vec{0} = c_1 A \vec{v}_1 + \dots + c_k A \vec{v}_k = c_1 \lambda_1 \vec{v}_1 + \dots + c_k \lambda_k \vec{v}_k.$$

Subtracting (1)-(2) gives

$$\vec{0} = c_1 (\underbrace{\lambda_k - \lambda_1}_{\neq 0}) \vec{v}_1 + \dots + c_{k-1} (\underbrace{\lambda_k - \lambda_{k-1}}_{\neq 0}) \vec{v}_{k-1} + c_k (\cancel{\lambda_1 - \lambda_k}) \vec{v}_k \overset{\cancel{\lambda_1 - \lambda_k}}{\neq 0}$$

$$\implies c_1 = \dots = c_{k-1} = 0 \quad (\text{since } \vec{v}_1, \dots, \vec{v}_{k-1} \text{ are L.I.}).$$

But then the original equation reduces  $\vec{0} = c_k \vec{v}_k \rightarrow c_k = 0$ .  $\square$

Theorem: If the eigenvalues of  $A$  are distinct (and real), then a basis of  $\mathbb{R}^n$  consisting of eigenvectors of  $A$  exists.

"A-eigenbasis"

Proof: For each of the  $n$  eigenvalues, there's an eigenvector. Apply the Lemma.  $\square$

Remark: The existence of an  $A$ -eigenbasis is crucial for being able to write a given vector as a sum of eigenvectors of  $A$ , as part of solving systems of difference/differential equations, etc.

Given an eigenbasis  $\vec{v}_1, \dots, \vec{v}_n$ , write  $P = \begin{pmatrix} \vec{v}_1 & \dots & \vec{v}_n \end{pmatrix}$  and compute  $AP = \begin{pmatrix} \vec{v}_1 \\ A\vec{v}_1 \\ \vdots \\ A\vec{v}_n \end{pmatrix} = \begin{pmatrix} \vec{v}_1 \\ \lambda_1 \vec{v}_1 \\ \vdots \\ \lambda_n \vec{v}_n \end{pmatrix}$ ; assemble the eigenvalues into a diagonal matrix  $D = \begin{pmatrix} \lambda_1 & & 0 \\ 0 & \ddots & 0 \\ & & \lambda_n \end{pmatrix}$ , so that  $PD = \begin{pmatrix} \vec{v}_1 \\ \lambda_1 \vec{v}_1 \\ \vdots \\ \lambda_n \vec{v}_n \end{pmatrix}$ . Hence  $AP = PD$  and

$$(\dagger) \quad A = P \cdot D \cdot P^{-1}$$

(equivalently,  $P^{-1}AP = D$ ). We have diagonalized  $A$ .

Corollary 1: A matrix with  $n$  distinct eigenvalues can be diagonalized (or "is diagonalizable").

Ex 1 / Diagonalize  $A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$ . From before 23,

$A$  has

eigenvalues:  $\underbrace{0, 0}_{\text{multiplicity 2}} , 3$  — recall characteristic polynomial was  $\lambda^2(\lambda - 3)$ .

eigenvectors:  $\begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$

So Lemma doesn't apply — in this case, check independence.

$$P = \begin{pmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}, D = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

eigenbasis

$$\text{Therefore } A = \underbrace{\begin{pmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}}_P \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{pmatrix}}_D \underbrace{\begin{pmatrix} \frac{1}{3} & \frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & -\frac{1}{3} & \frac{2}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix}}_{P^{-1}}.$$

So you don't need to have distinct eigenvalues in order to diagonalize. //

**Ex 2 / Is  $A = \begin{pmatrix} 5 & -8 & -21 \\ 0 & 0 & 7 \\ 0 & 0 & -2 \end{pmatrix}$  diagonalizable? If so, do it.**

eigenvalues:  $5, 0, -2$  (upper triangular)  $\rightarrow$  distinct  $\Rightarrow$  diagonalizable.

eigenvectors: row-reduce (if necessary) to find vector in null spaces of

$$A - 5I = \begin{pmatrix} 0 & -8 & -21 \\ -5 & 0 & 7 \\ -7 & 0 & 0 \end{pmatrix} \rightarrow \vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad D = \begin{pmatrix} 5 & & \\ 0 & & \\ & & -2 \end{pmatrix}$$

$$A - 0I = \begin{pmatrix} 5 & -8 & -21 \\ 0 & 7 & 0 \\ 0 & -2 & 0 \end{pmatrix} \rightarrow \vec{v}_2 = \begin{pmatrix} 8 \\ 5 \\ 0 \end{pmatrix} \quad \Rightarrow \quad P = \begin{pmatrix} 1 & 8 & -1 \\ 5 & 5 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$A + 2I = \begin{pmatrix} 7 & -8 & -21 \\ 2 & 7 & 0 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \vec{v}_3 = \begin{pmatrix} -1 \\ -7 \\ 1 \end{pmatrix}$$

**Ex 3 / What about  $A = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 1 & 0 & 3 \end{pmatrix}$ ?** Eigenvalues:  $2, \underset{7}{(3)}$  w/multiplicity 2

Find eigenvectors:  $A - 2I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$  w/  $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$  spans  $E_2$ .

$$A - 3I = \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$
 w/  $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$  spans  $E_3$ .

Up to scale, there are only 2 eigenvectors. So there's no  $A$ -eigenbasis of  $\mathbb{R}^3$ , and  $A$  isn't diagonalizable. //

## Applications

- ① The determinant of a diagonalizable  $n \times n$  matrix is the product of the  $n$  (not necessarily distinct) eigenvalues:

$$\det A = \lambda_1 \cdot \lambda_2 \cdots \lambda_n.$$

Why?  $\det A = \det(PDP^{-1}) = \det P \cdot \det D \cdot \det P^{-1}$   
 $= \det D = \det \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{pmatrix} = \prod_{i=1}^n \lambda_i.$

(In fact, this is still true even if  $A$  isn't diagonalizable: we still have  $\det(A - \lambda I) = (\lambda_1 - \lambda) \cdots (\lambda_n - \lambda)$  by (\*), with constant term  $\lambda_1 \cdots \lambda_n$ . But another way to compute this constant term is by setting  $\lambda = 0$ , giving  $\det(A - 0I) = \det(A)$ . So  $\det(A) = \lambda_1 \cdots \lambda_n$ .)

- ② Compute  $\underbrace{\begin{pmatrix} 1 & 3 \\ 4 & 2 \end{pmatrix}}_A^{10}$  by diagonalizing  $A$ :

$$A = PDP^{-1} \text{ where } D = \begin{pmatrix} -2 & 0 \\ 0 & 5 \end{pmatrix}, P = \begin{pmatrix} 1 & 3 \\ 1 & 4 \end{pmatrix}$$

$$\begin{aligned} \Rightarrow A^{10} &= (PDP^{-1})^{10} = \cancel{P} \cancel{D} \cancel{P^{-1}} \cdot \cancel{P} \cancel{D} \cancel{P^{-1}} \cdot \cancel{P} \cancel{D} \cancel{P^{-1}} \cdot \dots \cdot \cancel{P} \cancel{D} \cancel{P^{-1}} \\ &= P D^{10} P^{-1} = \begin{pmatrix} 1 & 3 \\ 1 & 4 \end{pmatrix} \begin{pmatrix} (-2)^{10} & 0 \\ 0 & 5^{10} \end{pmatrix} \begin{pmatrix} \frac{1}{3} & -\frac{3}{4} \\ -\frac{1}{3} & -\frac{1}{4} \end{pmatrix} \\ &= \frac{1}{7} \begin{pmatrix} -4 \cdot 2^{10} & 3 \cdot 2^{10} \\ -3 \cdot 5^{10} & -3 \cdot 5^{10} \\ \hline 4 \cdot 2^{10} & -3 \cdot 2^{10} \\ -4 \cdot 5^{10} & -4 \cdot 5^{10} \end{pmatrix}. \end{aligned}$$

### (3) Stochastic matrices

Let  $A$  be an  $n \times n$  matrix with all positive entries, whose column sum to 1. (This is called a regular stochastic matrix.)

- $A$  has a steady-state vector, i.e. eigenvector with eigenvalue 1:

Since columns of  $A$  sum to 1, columns of  $A - I_n$  sum to 0

hence belong to an  $(n-1)$ -dim'l subspace of  $\mathbb{R}^n$  and cannot all be independent  $\Rightarrow \text{rank}(A - I_n) \leq n-1 \Rightarrow$

nullity  $(A - I_n) \geq 1$ . In fact, by a careful examination of

$A - II$  — picture:  $\begin{pmatrix} - & + & + & \dots \\ + & - & + & \dots \\ + & + & - & \dots \\ \vdots & & & \ddots \end{pmatrix}$  — one can deduce

that  $\dim E_1 (= \text{nullity } (A - I_n)) = 1$ , so the steady-state vector is unique (provided we scale it to have its entries sum to 1). That is, the multiplicity of the eigenvalue 1, is 1.

- Any eigenvector with a different eigenvalue than 1

(a) must lie in the plane  $x_1 + \dots + x_n = 0$

(b) must have eigenvalue  $\in (-1, 1)$

(b) is important for dynamical systems / Markov chains —

if the initial state is  $\vec{x}_0 = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots$

and  $\vec{v}_1$  = steady state vector, then

$$\vec{x}(t) = A^t \vec{x}_0 = c_1 \vec{v}_1 + c_2 (\lambda_2)^t \vec{v}_2 + \dots \xrightarrow[t \rightarrow \infty]{\text{limit}} c_1 \vec{v}_1$$

$0 \text{ since } |\lambda_2| < 1$

- EXAMPLE:

$2 \times 2$  matrices:  $A = \begin{pmatrix} a & 1-b \\ b-a & b \end{pmatrix} \Rightarrow A - \lambda I_2 = \begin{pmatrix} a-\lambda & 1-b \\ b-a & b-\lambda \end{pmatrix}$

 $\Rightarrow \det(A - \lambda I_2) = \lambda^2 - (a+b)\lambda + (ab - 1) = 0$ 
 $\Rightarrow \lambda = \frac{a+b \pm \sqrt{(a+b)^2 - 4(ab-1)}}{2} = \begin{cases} 1 \\ ab-1 \end{cases}$ 

Since  $0 < ab < 2$ ,  $-1 < ab-1 < 1$  as desired.